

CULTURED PEARL CLASSIFICATION EQUIPMENT DEVELOPMENT

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ASSOCIATION (INC)**

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Cultured Pearl Classification Equipment Development

Report on Initial Feasibility Study

Prepared for The Pearl Producers' Association Of WA

15th May, 1995

Principal Investigator:

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by

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Researchers:

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1. Introduction

This report covers work carried out at Applied Sorting Technologies Pty Ltd (AST) on behalf of the Pearl Producers Association of WA for Fisheries Research and Development Corporation into the feasibility of automatic grading techniques for pearls. The project was initially defined in terms of the requirement for a consistent pearl quality classifying instrument, capable of accurately and repeatedly inspecting pearls placed in the instrument, returning (via screen and hard copy) a report on the pearl quality indicators -

colour
shape
size
lustre
surface blemishes.

However, it became quickly clear that the industry expected an on line classifier working at production rates capable of carrying out automatic placement of pearls in their different "quality" parcels. The emphasis then shifted toward carrying out a preliminary screening classification perhaps not to the accuracy of a trained grader, but able to do a useful and fast pre-sort, saving grader time to concentrate on the more skilled end of the grading process.

Although all of the above variables were examined, the results of the study, combined with industry feedback, suggest that the most useful form of machine would be one that classifies according to shape, colour and size, leaving the more difficult lustre and blemish measurements (initially at least) to the grader. A conceptual machine has been outlined which would be able to carry out this abbreviated task continuously at a rate approaching a pearl each few seconds.

The project concentrated on designing and building a flexible measurement station, together with the necessary image processing hardware and software for acquiring pearl characteristics, and development of decision-making paradigms for assessing accuracy in the above parameters compared to human grader examples. The pregraded samples provided by Broome Pearls formed the basis for developing rules of classification, and were used to evaluate especially the shape routines developed during the study.

This report consists of a drawing together of a number of interim reports provided during the course of the project, together with results of concluding tests carried out following the report to the PPA Annual General Meeting in October, 1994 on shape classification and colour.

The emphasis during the work was on the evolution of practical measurement techniques with potential to be transferred to useful equipment. Hence there was not a major emphasis on backgrounding any other research in the field. Experience in the development of a range of diamond classification machines for Argyle Diamond Mines was used in determining the approaches to practical machine planning.

2. Summary

The scope of the project proved in practice to be more extensive than initially planned. As result, only the *shape* parameter has been "automated" to degree initially intended for all measurements. This has in fact demonstrated the intended way in which the system would be controlled and operated. It has exhibited good results on the initial carefully chosen groups of pearls, but further investigation is necessary as demonstrated by somewhat poorer results on much larger samples made available toward the end of the work.

Some problems with software have delayed this side of project - eg it was intended to have had by the end of the work an equivalent routine for size, but the script (macro) version of Global Lab Image for returning major axis length routine has an as yet unfound bug and so this has been deferred until a following phase.

Non-shape parameter procedures have been trialled manually on a limited number of pearls supplied by Broome Pearls. The general opinion is that *shape* and *size* can meet requirements (once the industry and in particular graders become more familiar with the objective nature of the process). *Flaws* can be automatically identified but the procedure is time consuming due to the need to scan the whole pearl surface in detail. It would be difficult to do more than count and size such defects. *Lustre* appears to be usefully characterised by reflections of structured illumination sources, although with the samples available there hasn't been the chance to fully quantify this. *Colour* at present would seem to be confined to the more obvious changes - yellow from white/blue/grey has been confirmed on limited samples but the spherical mirror nature of the pearl means this task is difficult. A different approach using a fibre optic- coupled spectrophotometer close to the pearl surface has been usefully demonstrated at least in an initial form, and could be readily transferred to an integrated rig. It may allow blues and blue/greys to be separated as well as yellows.

Mechanical handling with stepper-motor controlled vacuum probes for presentation of the pearl in different views has been found to have some minor limitations when dealing with grossly irregular pearls. Some more work is needed here based on not releasing the vacuum grip when carrying out the shape procedure. However we would need to remove the influence of the holding probe from the image (eg digital image subtraction or accurate Region of Interest masking).

Mechanical speed would probably need to be increased for a useful sorting machine, primarily through a reduction in the number of pearl movements during a cycle, and through the use of larger stepper motors.

2.1 Future Investigations

Following reporting to potential users at the AGM of the PPA in October, 1994, feedback suggested that there was interest in a classifying system based on the work carried out during this project, based on grouping pearls by shape, size and colour, whilst carrying out accurate counting of batches being so classified.

A number of aspects of the classification systems for such a shape/colour/size equipment would need further work to extend and improve on the work to date. These would ideally be the subject of a Phase 2 study, and would include -

- mechanical singulation / orientation / presentation station with mechanical feed arrangement to encourage pearls to align along their long axis for presentation to the horizontal pickup probe
- system to capture images without releasing the horizontal vacuum holder (to save process time)
- confirmation of the ability to use a much lower number of shape views (say 4 cf current 16)
- investigation of some more advanced classification routines on the shape spherical harmonic data
- extension of the classification routine to colour data from fibre optic probe system
- realisation of fast spectrometer for fibre optic probe system.

Such a Phase 2 aim would be toward early realisation of a relocatable piece of equipment that might not be able to operate at full production speed requirements, but would give graders a chance to look in detail at the types of decisions the machine is capable of giving. It would encourage them to evaluate the basis of their own decision making, (in particular in the possible definition of subgroups within a particular shape class that the computer could more easily recognise, and eventually recombine) and thus provide excellent feedback for the detailed design of a full production equipment.

An estimated production cost in very low numbers after removal of further research costs and production engineering costs would be around \$75,000 per unit. The throughput rate would be around a target of 1 pearl per second. Development cost estimates for such a Phase 2 relocatable prototype, without final form of output separation system is expected to be in the range of \$100,000 to \$150,000.

A drawing showing the essential parts of a possible final equipment is sketched below as fig.1. It indicates discharge of each pearl into an appropriate physical output category via transfer to a carousel with a large number of possible divisions.

Possible prototype
classifying system

20/2/95

Computer
+ electronics

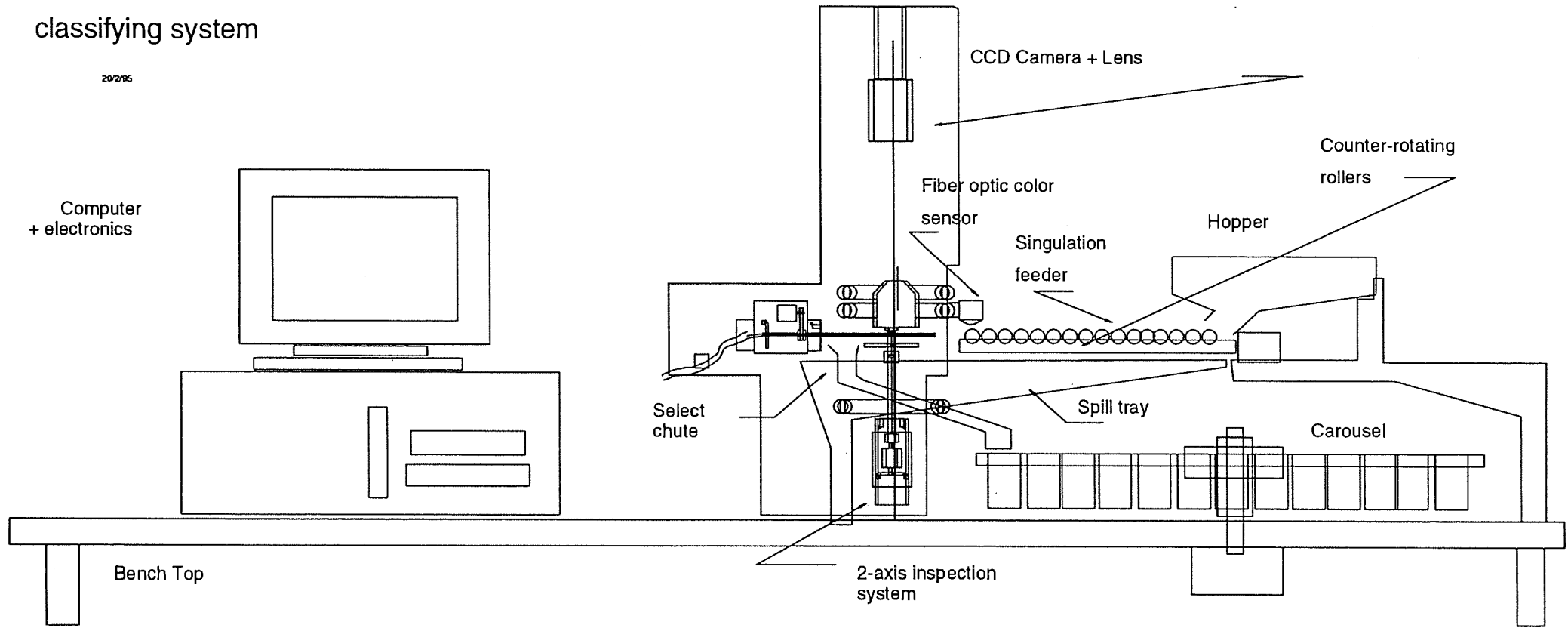


Fig. 1

3. Measurement Station

A large part of the initial phase of this project largely involved designing and building a flexible pearl inspection station. This unit is shown in figs. 3 & 4 and the drawing shown in fig. 2, and a video of its operation was shown at the PPA Annual General Meeting.

The system was constructed to allow, under computer control, the translation and rotation of pearls placed individually in the sample holder. Reasonable pearl stability on all except the extreme shaped baroques was achieved through the use of solenoid-controlled vacuum, for which special rotating vacuum bearings were designed.

By means of stepper motors driven by a Windows program [PEARL], it was possible to present any part of the pearl surface to the colour CCD video camera, and hence to the image acquisition printed circuit board and proprietary image measurement program Global Lab Image (GLI). A sequence of commands can be given to the PEARL program to accomplish a series of movements. The same program is able to coordinate and command the GLI image acquisition and processing steps.

The equipment has been developed with three different forms of lighting in order to enhance the optical characteristics of the pearl under inspection. These were:

- Backlit - using small circular fluorescent tubes placed below the base table. The view of the pearl from the camera is such that it appears in silhouette against a diffusely illuminated perspex background. This arrangement is used for shape and size measurements.
- Frontlit - using diffuse light from a translucent walled optical chamber enclosing the pearl. This chamber is illuminated by a pair of circular fluorescent lamps. It was used for the initial colour measurements.
- Frontlit - using structured lighting, for lustre and flaw measurements, where the pearl surface is considered more or less as a spherical mirror. The camera then looks at deviations from this ideal.

The whole mechanical-optical arrangement together with software control was designed with a final machine application in mind. Included in this is the ability to use the results of the GLI measurements to guide the path of following measurements. For example, it may be necessary to align the long axis of a drop-shaped pearl so that the axis is parallel to the horizontal probe axis. This can be done by steps involving GLI measuring the pearl's major axis with respect to the horizontal probe axis, commanding then the rotation around the vertical axis by the measured amount to achieve the desired alignment.

An alternate rig was used for the second series of colour measurements (see section 8. below). This arrangement consisted of an optical fibre bundle, white light source and scanning monochromator.

Pearl Classification Project

2-axis inspection rig

ph, nov 93

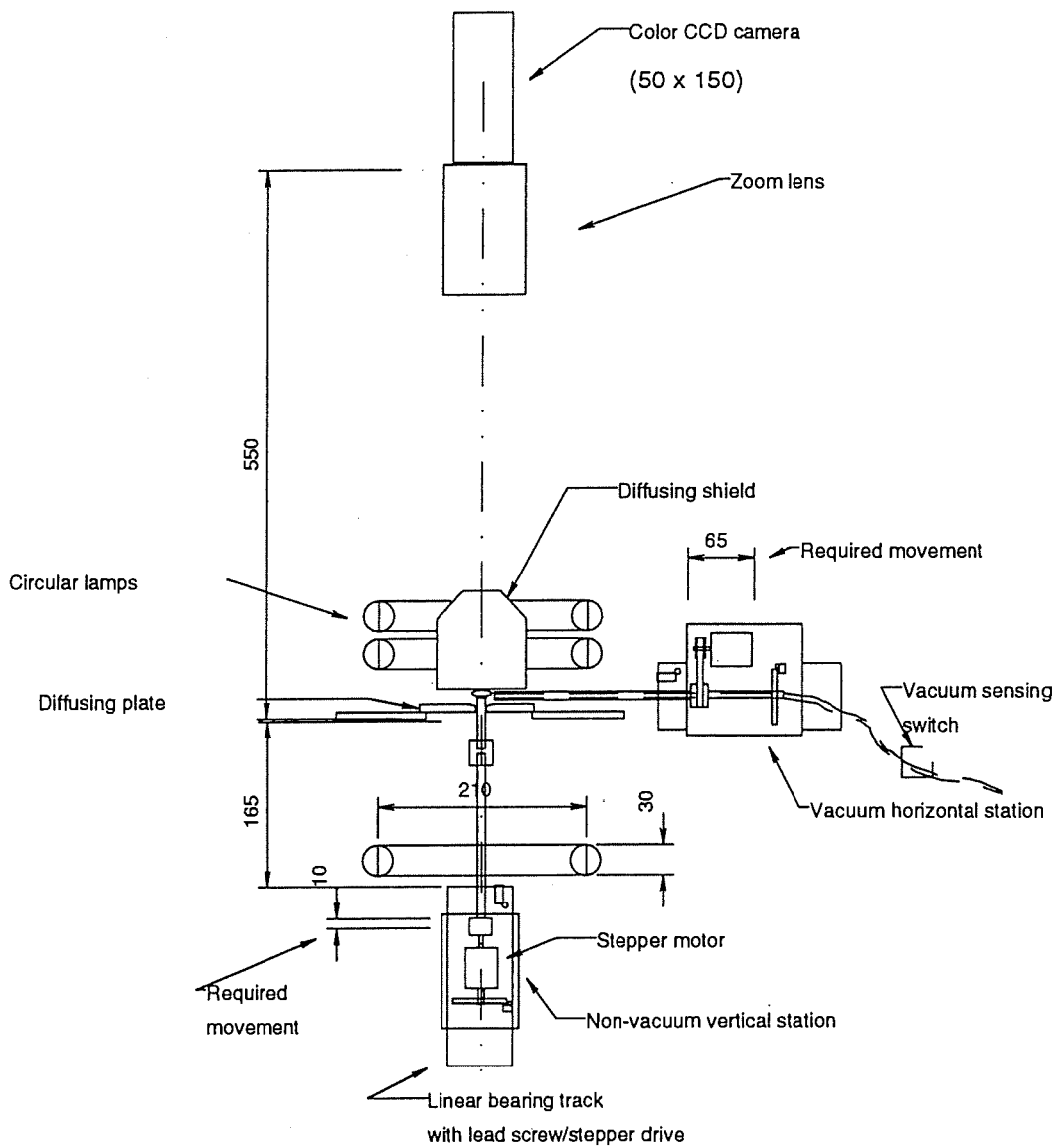
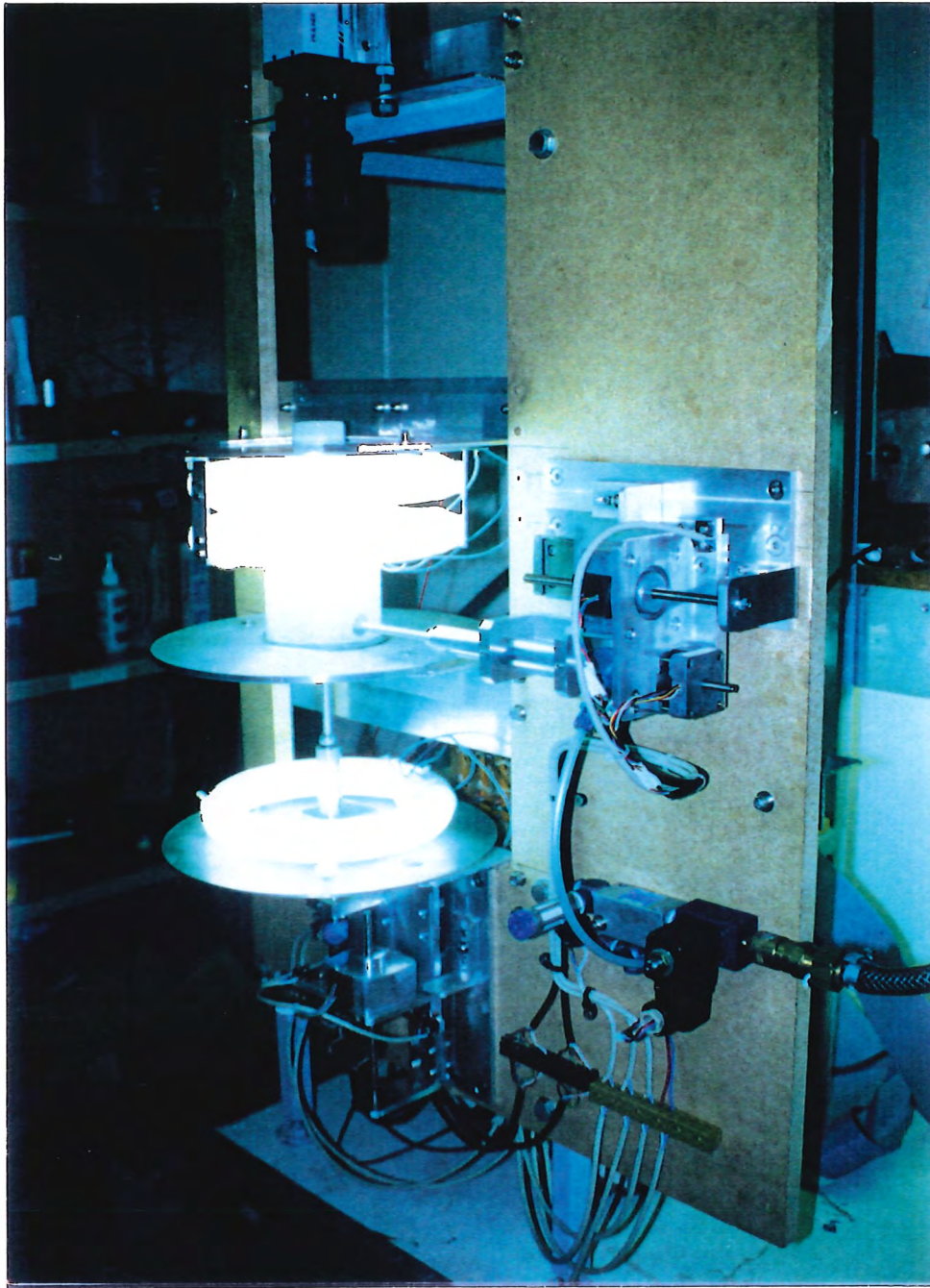
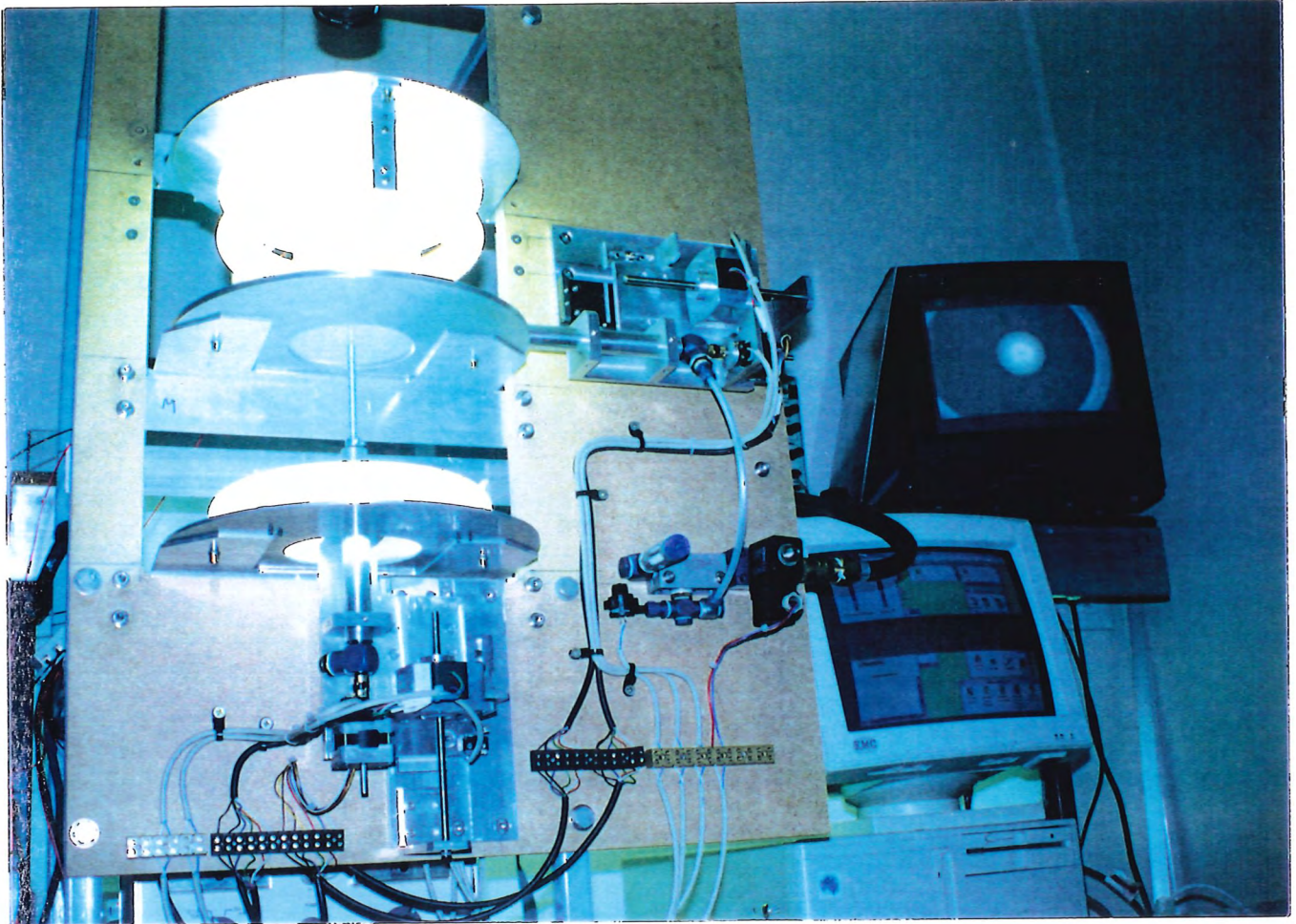


Fig. 2



View of Measurement Station

featuring horizontal translation/rotation stage, and showing top illumination diffuse chamber with CCD camera above



View of Measurement Station

featuring vertical translation/rotation stage, and colour monitor showing top illuminated image of pearl

3.1 Inspection Machine Considerations

The details of the hardware sub-systems used in the Phase 1 setup are set out below:

Computer:	486 - DX66 PC with 8 Mb RAM
Data Translation	DT55 (black/white) "Quick capture" frame capture board
Data Translation	DT2851 (HSI colour) frame capture board
Pulnix TMC 76	CCD camera with c-mount Zoom lens

Low power stepper motors (4), with drive boards and PC control via special Windows-based operating program

Light sources NEC Miniature 20W circular fluorescent lamps for front and rear illumination

20 watt strip fluorescent lamps for structured illumination

Vacuum chuck for presenting pearls horizontally

Rotating vacuum bearings for sample rotation

Lead screw/linear bearings for translation

Cycle time for typical procedure;

eg *shape* 16 views, approx 2 seconds per view after first pick up.

This is dominated by slow stepper motor. A more powerful stepper motor could be used to improve motor speed by between 2 and 4 times. A fast image processing computer could be chosen to run very rapid calculations. A reasonable target may be to carry out a shape measurement in under 2 seconds.

Note the possibility that several parameter measurements could be derived from the same mechanical procedure.

The longest procedure is that of flaw detection, which needs about 360 views to cover a whole surface. Small angular steps are needed so the mechanical arrangement could be continuous, with a frame rate (50Hz) image processing system. Rapid "blob" analysers are now available which may allow over 1000 views per second, which could be used if the pearl is rapidly rotating.

It has been found difficult to keep track of location of flaws due largely to mechanical imprecise transfer of the pearl from one axis to the other. This is especially so for strongly non-spherical shapes. There is a general problem with these shapes in the present set up. Some modifications have been discussed which may assist this problem in the next phase.

4. Size

The approach to pearl size measurement adopted here has been based on extraction via computer imaging routines, of the major diameter of the shadow of the backlit pearl taken in a number of orientations. Ideally an infinite number of orientations would be used, and the smallest major diameter so found would be used as the best approximation to a "sieve size". In fact, in most measurements reported here, an automatic procedure was followed whereby four views were taken during a series of four x and y axis rotations.

The method in general will tend to overestimate the pearl size when only a few projections are used, as the smallest major diameter may not be found. However the pearls have relatively slowly changing outlines, enabling reasonable assessment to be made from such few projections.

Calibration of the system is carried out by introducing precision ball bearings into the measurement station, of approximately the same size as the pearls under test. The Global Lab Image system allows the teaching of the transformation measurements between the image and the real world.

A number of tests were then carried out on pearl samples. The results are summarised in tables of figs 5 & 6.. The first used the initial (AS) series of pearls (see table in fig. 7), all labelled Size 10/11 mm, with 24 pearls covering all 6 Broome Pearl shape categories. As could be anticipated, the most irregular shapes (baroque) gave the largest difference between micrometer measured size and image derived size, but all except 2 of the 24 were well within 0.5mm of the micrometer size, with most of the non-baroque being closer than 0.2mm. (refer to fig. 5) With no proper pearl screens at our disposal, a micrometer was used to estimate the minimum circular opening through which a particular pearl would pass.

A further test was carried out with 10 samples of each of the 5 shape groups in the Broome Pearls second series (no baroques), and minimum, average and maximum image sizes presented in the table in fig. 6B, with the samples tested all labelled as 10/11 mm size. Again the image derived size data matched closely the labelled size.

A final test was carried out using 15 low quality pearls taken from previously supplied feed test samples. These covered the size range from 9 to 14 mm. As the table in fig. 6A shows, the computer image derived sizes correlated to micrometer sizes to a correlation factor of 0.99942 - very good indeed - and fig. 6C shows the size comparison across the size range.

We are confident that this measurement can be tied down well in a practical system. The operational speed is limited by the number of views needed and the time taken to transfer samples between vertical and horizontal vacuum probes, probably taking ~1 second per view in a realistic system. This would be a combined measurement with that of shape, with some of the shape projections being used to compute size. However, unlike the proposed shape regime, the size procedure would be slowed slightly by the need to rotate around two axes.

The current rig did have some difficulty in manipulating the extreme baroque shapes - it is believed that by slight redesign of the probe design and pickup/image capture sequence, these mechanical difficulties can be overcome.

		Micrometer size		Computer size		Difference	
Pearl		mm		mm		mm	
(First BP Samples)							
	Round						
AS1		10.95		10.84		0.11	
AS2		10.85		10.77		0.08	
AS3		10.71		10.61		0.10	
AS4		10.90		10.80		0.10	
AS5		10.79		10.70		0.09	
AS6		10.16		10.08		0.08	
	Drop						
AS7		10.50		10.47		0.03	
AS8		10.32		10.31		0.01	
AS9		10.41		10.45		0.04	
	Button						
AS10		10.29		10.10		0.19	
AS11		10.15		10.01		0.14	
AS12		9.95		9.92		0.03	
	Semi-						
AS13	baroque	10.96		10.85		0.11	
AS14		10.90		10.86		0.04	
AS15		10.59		10.42		0.17	
AS16A		11.05		10.73		0.32	
AS16B		10.78		10.91		0.13	
	Baroque						
AS17A		10.60		10.92		0.32	
AS17B		10.90		11.60		0.70	
AS17C		11.80		11.15		0.65	
AS17D		11.00		11.56		0.56	
	Circle						
AS18		10.40		10.19		0.21	
AS19		10.79		10.47		0.32	
AS20		11.00		11.02		0.02	
Basis - 4 mutually orthogonal views - smallest of 4 major axis values							

Size Measurements - Smallest Major Axis basis - 15 low quality pearls

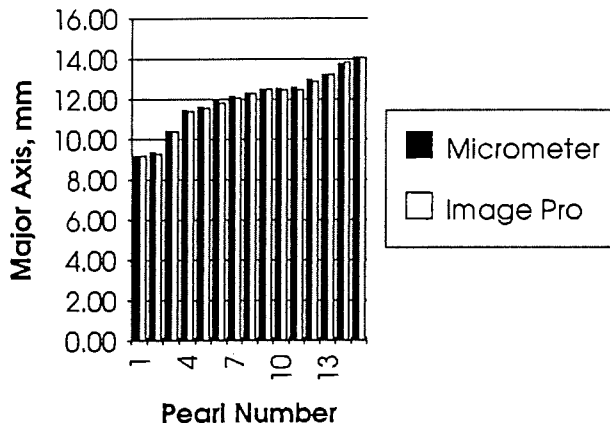
(a)

Micrometer Image Pro

9.17	9.17
9.35	9.29
10.41	10.40
11.45	11.39
11.61	11.56
11.91	11.81
12.15	12.08
12.33	12.30
12.49	12.51
12.53	12.47
12.59	12.48
12.97	12.88
13.23	13.24
13.77	13.83
14.10	14.06

(c)

Size Measurements



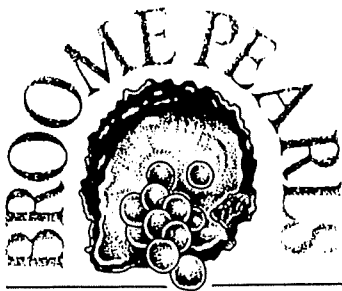
Correlation

	Column 1	Column 2
Column 1	1	
Column 2	0.99942	1

(b)

Size Measurements on 10 New Samples per shape group - all labelled 10/11mm

Shape	Minimum	Average	Maximum
Round	10.21	10.57	10.85
Drop	9.95	10.49	10.80
Button	10.64	10.87	11.10
Semi-baroque	10.04	10.42	10.76
Circle	10.21	10.50	10.87



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7 September 1993

Applied Sorting Technologies
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 BULLEEN VIC 3105

CONSIGNMENT

LOT NO	SIZE	PIECES	DESCRIPTION	MOMME	TOTAL AUD
AS 1	10-11	1	Round grade 1	0.53	100.00
2	10-11	1	Round grade 2	0.49	100.00
3	10-11	1	Round grade 3	0.49	100.00
4	10-11	1	Round grade 4	0.50	100.00
5	10-11	1	Round blue/grey	0.48	100.00
6	10-11	1	Round yellow	0.38	100.00
7	10-11	1	Drop grade 1	0.52	100.00
8	10-11	1	Drop grade 2	0.46	100.00
9	10-11	1	Drop grade 3	0.49	100.00
10	10-11	1	Button	0.40	100.00
11	10-11	1	Button blue/grey	0.34	100.00
12	10-11	1	Button yellow	0.34	100.00
13	10-11	1	Semi baroque grade 1	0.53	100.00
14	10-11	1	Semi baroque grade 2	0.56	100.00
15	10-11	1	Semi baroque grade 3	0.56	100.00
16	10-11	2	Semi baroque blue/grey	0.98	200.00
17	10-11	4	Baroque white/grey	2.26	400.00
18	10-11	1	Circle	0.48	100.00
19	10-11	1	Circle blue	0.53	100.00
20	10-11	1	Circle yellow	0.65	100.00
				<hr/>	<hr/>
				24	2,400.00
				<hr/>	<hr/>

GOODS ARE DELIVERED ON CONSIGNMENT SUBJECT ONLY TO CONDITION THAT THE GOODS ARE AT THE RISK OF THE CONSIGNEE UNTIL RETURNED IN ORIGINAL STATE AND GOOD CONDITION AND THAT THE CONSIGNEE IS LIABLE FOR ANY LOSSES OR DAMAGE HOWEVER INCURRED.

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DATE:

SIGNATURE: *DR Norman*

5. Shape Classification

A large part of the project effort went into the investigation of pearl shape classification by machine training.

Following discussions with Prof Nugent of Melbourne University regarding appropriate 3-dimensional descriptors for shape representation, it was decided to use a back projection technique (see appendix 1 for details). Here in a fashion similar to X-ray CAT scanning procedures, a series of back-lit "shadows" of each pearl would be stored in the computer video frame store, and for each, a set of boundary coordinates would be automatically extracted.

A software procedure for extracting spherical harmonic series from the set of such boundaries was written and tested on mathematically generated model shapes. The two sets of coefficients generated by this procedure characterised (a) the rotation of a radius vector around 360 of the perimeter, with (b) rotation of the pearl to present 16 profiles or shadows. Appendix 2 has further details.

It was found that for most pearls, there was substantial symmetry around a major ellipsoidal axis, (ie the perimeter set of data were the same for the 16 views as long as rotation around the long axis of symmetry was chosen). As a major amount of time is used in rotating and capturing images of each view, savings such as this are potentially very important. Obviously, suitable mechanical means would have to be found in an automatic machine to ensure correct orientation.

5.1 Processing Details

Initially the coefficients of the spherical harmonic series were loaded into an Excel spread sheet for a series of training sets of pearls (see fig 7 for description). This spread sheet took numbers (coefficients) from each individual pearl in each predefined shape group, and calculated average values for each of the coefficients (1-8), suitably normalised to the zeroeth coefficient. Test pearl data could then be introduced, one at a time, and a least distance algorithm used in order to quantify divergence away from the average as a single number (sum of magnitude of differences).

For an "unknown" test pearl, this procedure would be carried out comparing its spherical harmonic coefficients with the average of each of the training shape groups, adding each time the magnitude of the differences between the test harmonic and the training average harmonic. By adding these differences, the closest fit would be the training shape class with smallest difference in this set of numbers.

Other ways of training and evaluating are available, most being mathematically more sophisticated than this least distance procedure, eg artificial neural networks. It may be useful in a future phase of the development process to investigate these other classification algorithms, still using the data generated via the spherical harmonic series as the numerical description data for each pearl.

Figs 8 - 10 show in graphical form the relationship of coefficients up to the eighth harmonic for one of each of the six different shape types supplied in this sample from Broome Pearls. The table in fig. 11 is the result of the self application procedure (ie training set identical to test set, being pearls listed in fig 7).

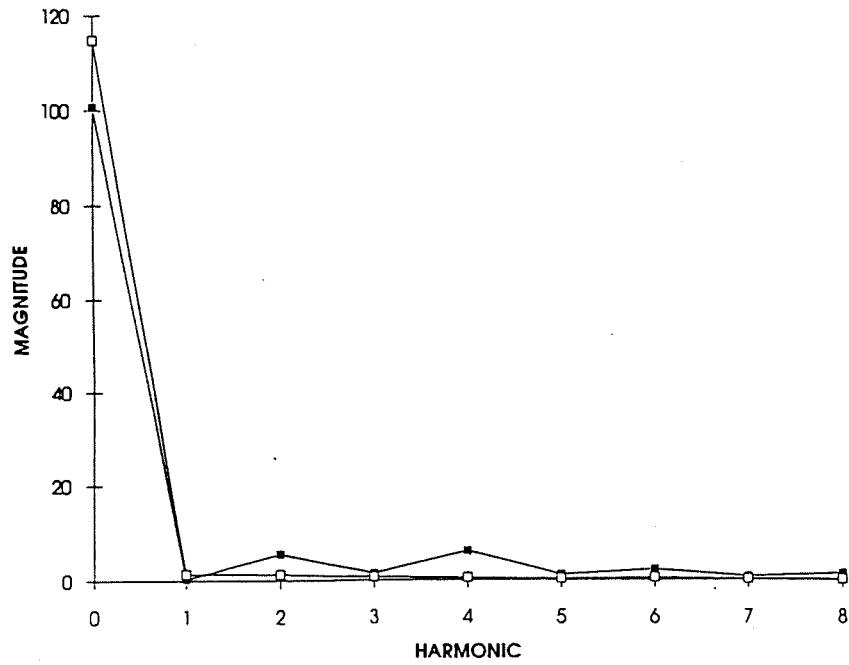
This showed that the pre-categorised pearls were quite consistent and well clustered, with only the semi baroque group having a couple of misclassified examples, in that only 2 of the 5 examples in that group were closer to the semi baroque average than the averages of other categories (1 drop, 1 round and 1 button). Because of the small number of pearls (maximum of 6 in any one shape category), it wasn't practical to set the usual one half of each group aside as the test set with the remaining half the training set.

Subsequently, a much larger test set of classified pearls from Broome Pearls (~ 50 per shape group) was obtained including all except the baroque category (as this category was found to be highly distinctive, and hence readily identifiable). The initial (AS series) shape data was then used as the training set for evaluating the method, and the second series was used as the evaluation set. In order to carry out the classification process in reasonable time for the larger number of pearls, a further C program was written to replace the least distance spread sheet classifier.

The following then was the final procedure for this shape sorting exercise:

- the PEARL Windows program is the main program, controlling presentation of the pearl to the imaging camera via translation and rotation commands with vacuum hold down.
- embedded in PEARL is a Global Lab Image script routine which, under PEARL control, captures each image view and finds perimeter pixel coordinates. PEARL then computes the centroid value for each shadow image, and writes centroid and perimeter coordinate data for each of the 16 views to a data file.
- a DOS program, PDATA, currently running separate to PEARL but with the capability to be incorporated into the main program, carries out the following steps -
 1. it computes for each of the 16 views, the length of "radius" from centroid to perimeter for each of the 16 equal angular increments from 0 to 360.
 2. it then normalises these 16 lengths for each of the 16 shadow projections from the given PEARL filename to the largest radius (which is defined as = 1).
 3. it then applies the spherical harmonic series-generating program, FIT_2, to the resulting data, generating files with series of 8 coefficients;
- A further program, PCLASS, uses PDATA information to both train (learn) and classify pearls to and from 5 groups, viz round,, drop, button, semi-baroque, and circle. A typical output screen display from this program is shown in fig. 12.

AS7 - DROP GRADE 1



AS1 - ROUND GRADE 1

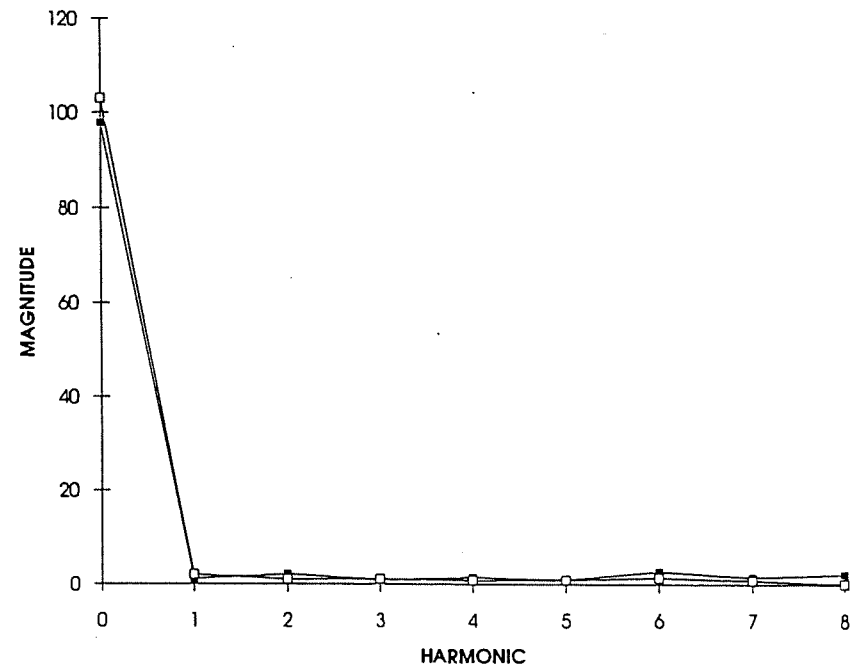
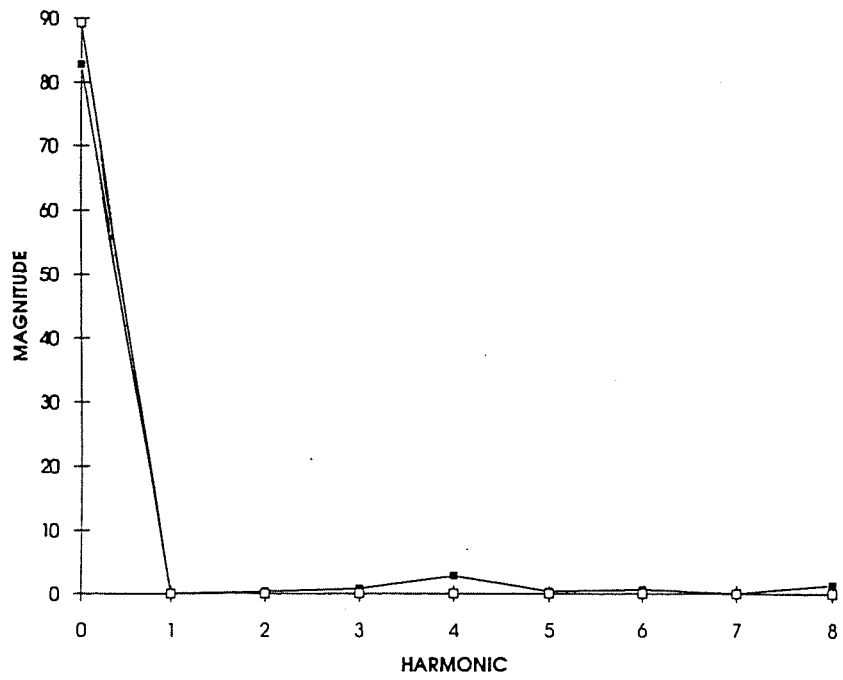


Fig. 8

AS11 - BUTTON BLUE/GREY



AS14 - SEMI BAROQUE

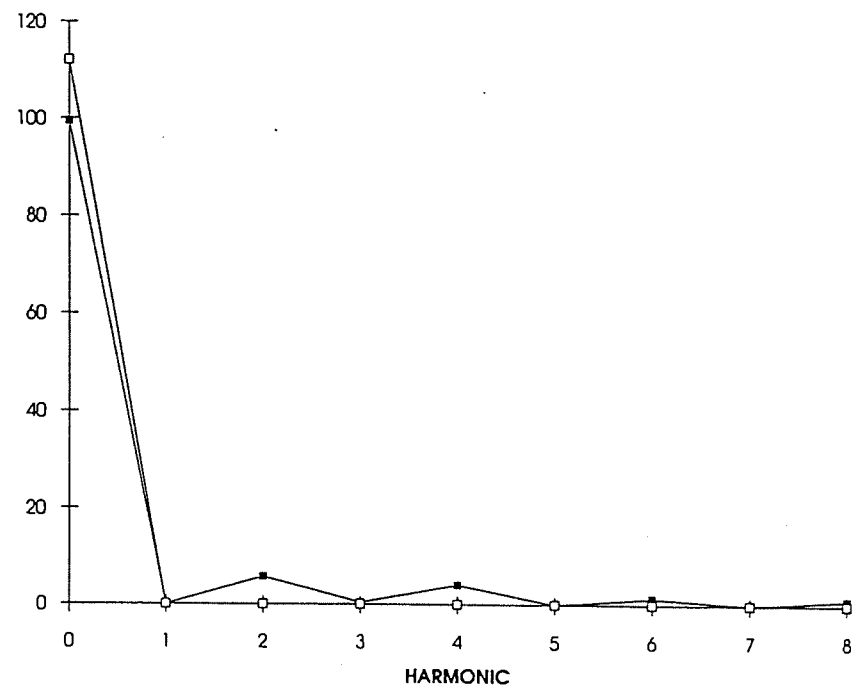
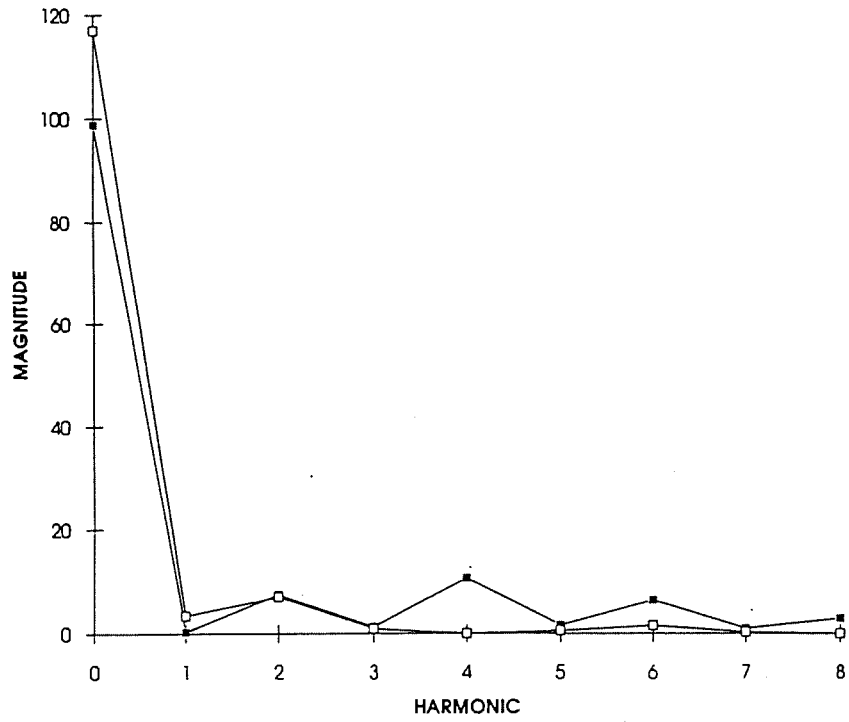


Fig. 9

AS17D - BAROQUE GREY/WHITE



AS18 - CIRCLE

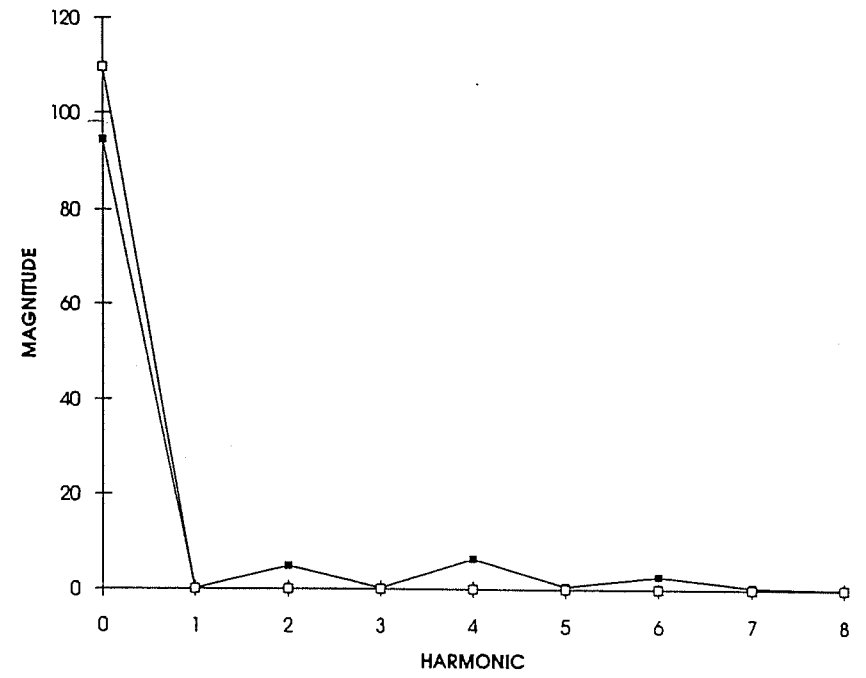


Fig. 10

Shape Tests - Least distance classifier with harmonics normalised to H0								
Pearl		Round	Drop	Button	Semi baroque	Baroque	Circle	Decision
AS1	Round	4.58	9.77	7.70	8.18	20.80	14.69	Round
AS2		1.06	9.27	4.53	4.92	25.01	14.15	Round
AS3		1.01	9.21	4.42	4.75	25.19	14.24	Round
AS4		1.02	9.21	4.42	4.75	25.19	14.24	Round
AS5		1.08	9.01	4.38	4.38	25.25	13.98	Round
AS6		0.91	8.61	4.28	4.43	24.82	13.38	Round
AS7	Drop	9.02	2.81	9.35	6.87	18.34	5.89	Drop
AS8		7.07	2.59	7.02	5.32	19.38	8.81	Drop
AS9		11.39	3.45	12.46	10.77	13.92	6.13	Drop
AS10	Button	4.76	9.75	1.08	5.21	26.97	14.41	Button
AS11		6.62	8.39	2.47	4.84	24.75	14.35	Button
AS12		3.63	10.13	2.18	6.35	27.00	15.72	Button
AS13	Semi-	5.91	10.05	2.69	3.90	27.17	14.47	Button
AS14	baroque	3.38	8.82	5.38	3.11	25.13	13.70	Semibaro
AS15		9.65	5.51	9.55	5.40	20.37	10.44	Semibaro
AS16A		9.45	5.27	8.40	5.91	19.85	7.99	Drop
AS16B		4.19	12.37	5.35	4.94	27.07	17.13	Round
AS17A	Baroque	23.83	16.86	25.89	23.57	7.65	12.62	Baroque
AS17B		26.55	20.43	26.90	23.60	9.62	18.63	Baroque
AS17C		26.58	18.40	27.70	26.00	8.65	15.66	Baroque
AS18	Circle	16.03	9.16	16.74	14.57	9.76	4.22	Circle
AS19		14.67	7.72	16.08	13.46	14.84	3.44	Circle
AS20		12.44	5.22	13.52	10.84	16.52	3.77	Circle

The image shows a terminal window with a dark background and light-colored text. At the top, the word 'classify' is visible. Below it, a table of classification results is displayed. The table has five columns: Pearl Type, Number, Harmonics, and two unlabeled columns. The first row shows the sample label 'ro' in the first column, '16' in the second, '8' in the third, and '60' in the fourth. The second row lists the pearl types: 'BUTTON', 'CIRCLE', 'DROP', 'ROUND', and 'SBAROQUE'. The third row shows numerical values: '4.659', '14.156', '9.168', '0.740', and '4.964'. The value '0.740' is highlighted in yellow.

Pearl Type	ro	Number	16	Harmonics	8	GO
BUTTON	CIRCLE	DROP	ROUND	SBAROQUE		
4.659	14.156	9.168	0.740	4.964		

Output Data Display from PData Classification Program

(showing machine selection of *round* (with minimum difference of 0.740) for sample labelled *ro16*, ie no. 16 example from *round* group)

5.2 Results of Larger Trial

Using the AS series 20 pearls in 5 shape groups as the training set, the 14th September consignment from Broome Pearls were measured as the test and evaluation set and the resulting data processed via the above routines. With unmodified training, the evaluation of the test sets resulted in the following classification results; (see appendix 3).

- *Round* Group BP 88 - 31 pearls, all placed correctly into the *Round* category;

- *Drop* group - BP 183 - 49 pearls
22 correctly into *Drop* category
23 into *Semi-baroque* category
3 into *Circle* category
1 into *Button* category

- *Button* Group - BP 241 - 29 pearls
12 into *Button* category
16 into *Round* category
1 into *Drop* category

- *Semi-baroque* Group - BP 303 - 50 pearls
9 into *Semi-baroque* category
27 into *Round* category
8 into *Drop* category
5 into *Circle* category
1 into *Button* category

- *Circle* Group - BP 32 - 49 pearls
18 into *Circle* category
17 into *Drop* category
8 into *Round* category
3 into *Semi-baroque* category
3 into *button* category

The table below illustrates the differences in classification by choosing different pearls to make up the training sets. It illustrates the degree of care needed in choice of pearls when making up a training set. For example, the only difference between sets 2 and 6 was that for 6, one extra button and one extra semi baroque were added to the AS series training set. As can be seen, circles and semi baroque identification improved slightly, but button recognition was reduced to only one of 30.

Training basis	Initial AS series with AS test set	AS series with 2nd test set	1st 1/2 of 2nd set	1st 1/2 of 2nd set with extra SB examples	AS series with added BU & SB	Middle 1/2 of 2nd series
	1	2	3	4	5	6
Round	6/6	31/31	9/31	23/31	15/31	31/31
Drop	3/3	22/50	28/50	22/30	21/50	18/50
Button	3/3	11/30	13/30	20/30	22/30	1/30
Semi-baroque	2/5	9/50	12/50	20/50	12/50	11/50
Circle	3/3	17/50	15/50	15/50	15/50	19/50
Baroque	4/4					

Importantly, it is noticeable that objective rules can only go a certain way toward automatic classification, with results heavily dependent on choice of training examples. The first small set (#1 above) were reasonably uniformly constituted and self-consistent, as shown by the table in fig. 11. as well as the above table. Appendix 4 shows shadow images of all AS series pearls.

Looking however at the second series, (#2 in above table), detailed results are given in tables in Appendix 3. In the Drop series, we can refer to example images in appendix 5, labelled DR##. The images in the Drop series are wrongly numbered, and we should subtract 10 to get correspondence with the table in appendix 3. Of the example images shown, only DR44 was classified as a drop when taught by the AS7-9 examples in the first series. Most of the others "leaked" to the semi-baroque category (AS13-16 training set). DR45 and DR55 images show extra lobes not encountered in the initial training set but suggested in the semi-baroque image AS14.

Button examples in appendix 3 show BU11 has been selected properly as a button, but BU12 however narrowly is selected as semi-baroque over button, whilst BU21 is quite spherical and is selected clearly as round over button.

Semi-baroque images which were selected as being semi-baroque were SB 13, 21, 24, 32, and 43, these being similar to training samples AS13-16. Most of the other images shown in the appendix 5 were drops, with a few of circles, button and round.

Circles with images in appendix 5 showed significant leakage across categories, especially to drops.

5.3 Discussion

There are a number of ways of improving this performance. One is to set tolerance limits for acceptable closeness of fit, so that a new category of "don't know" would cover pearl shapes which didn't fit well to any of the trained groups. In this way it would be preferable to have a defined difficult category which would need to be hand-sorted rather than having such examples leak across to other groups.

The second way would be to make a more thorough attempt to cover the different shape "sub-groups" within each overall shape group. This would allow a larger number of categories, eg DR1,2,3,4,5 etc, each having its own set of training examples. The overall classification system, could be readily adapted to then aggregate the subgroups as required.

A third possibility would be to set up overlap categories which may occur when the experienced grader might not see a large difference between two shape groups which an individual pearl may be able to be put. A suitable algorithm could be invoked to place the pearl into the most valuable of the two groups.

As well, there is the chance that a more sophisticated classification procedure, such as a suitably structured artificial neural network might improve the decision process.

6. Flaw Measurement

According to Lyman (Guide to Gems and Precious Stones, Simon and Schuster, 1986), flaws in cultured pearls are minor irregularities which are either small, almost conical, protuberances or more likely barely noticeable cavities in the surface which resemble lunar craters.

Because of the smooth spherical nature of pearls, we have found that a suitable way to find such surface flaws (cavities) has been to present the pearl in two x 360° rotations with axes of rotation 90° apart to the CCD camera to ensure viewing of the entire surface. The image captured for each step is that of a strip of light similar to a linear fluorescent tube. This produces a bright "image" of the light source on the surface of the pearl. As the pearl is rotated, the light area moves over the surface, and pits are seen as small "craters" with highly contrasting edges compared with the rest of the unblemished surface.

The GLI program can be configured to find such transitions by thresholding and feature area discrimination. The procedure for a whole pearl is reasonably lengthy, as we can't jump too many degrees in one step if we are to avoid missing small pits.

Typically the pit would remain detected by this routine over approx 5 - 10°, however some may require inspection at every 2°. In this case then, 360 images need to be examined for each pearl to cover the whole surface.

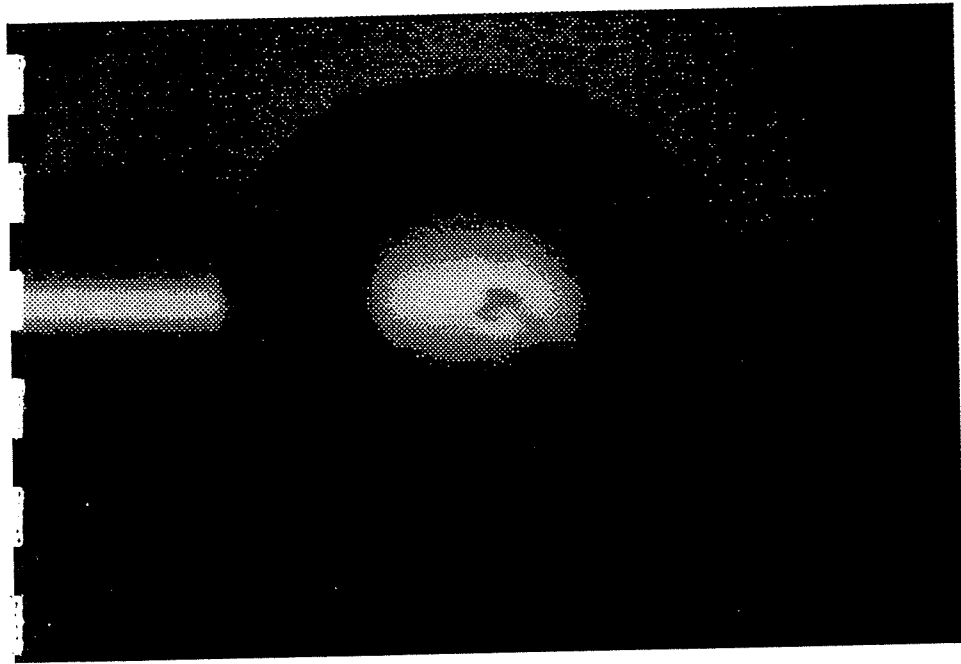
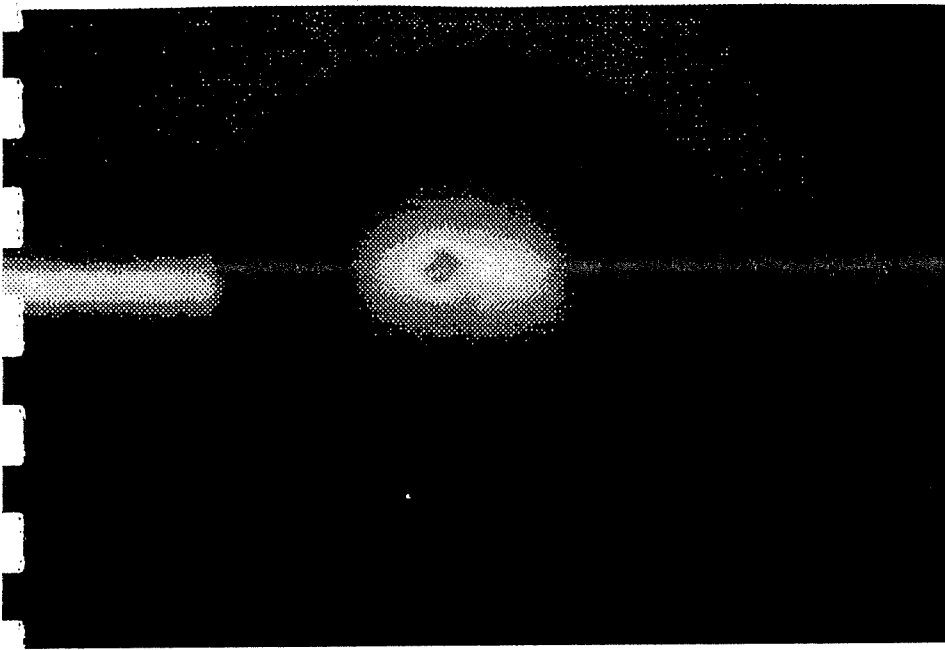
In the current setup, 1 pixel is equivalent to 0.06mm. We need at least 5 pixels for GLI to pick up the flaw as a separate entity.

Our initial estimate of the processing time required for finding "craters" in around 360 frames for one pearl was with a processor running at frame rate of 50 per second. Since then, in discussions with the CSIRO Division of Manufacturing Technology, we have found available "blob" analyser card systems designed by this group and subsequently manufactured and sold by Vision Systems, which are able to find blobs at a rate of more than 200 per second. Using this sort of image analyser, it would be possible to consider spinning the pearl at a high rate of say 180 steps per second, for complete rotation around one axis, then a 90 rotation around the orthogonal axis, followed by another high rotation scan of 180 steps in another second. The complete cycle would then take around 3 - 5 seconds. Whether flaw coordinates would be able to be stored at that rate would require detailed evaluation. However such a quick scan could possibly be used to screen and separate on a flaw/no flaw basis.

The other problem with the above scheme in practice is keeping track of the location of detected flaws which has proved a mechanical difficulty with the current handling system especially due to instability when larger irregular shapes are involved.

The images of a couple of flaws on pearl number AS4 (round) are shown in fig 13, and the table in fig. 14 shows the progression around one of the 360° scans, indicating the positions at which the Global Lab Image program found flaws, with the area of these flaws at each viewing angle. In some cases such as 3,4 7,8 11,12 and 20,21 two flaws appear simultaneously (hence the notation Flaw A and Flaw B).

The sensitivity of the technique is seen from this to be very high because of the optical magnification and the severe light and dark crater formations shown up by the structured lighting.



Flaw Image Examples.

Flaw Measurements					
					NB 1 pixel + 0.06mm
Sample AS4		Round Grade 4			
				Area of	2 degree steps
Flaw #	Rotational angle	detected flaw (pixels)			
		Flaw A	Flaw B		
1	20	13			
	22	11			
	24	12			
	26	10			
2	38	46			
	40	25			
3	42	8			
3	44	53			
3,4	46	90	6		
3	48	44	38		
3,4	50	49	7		
3	52	63			
3	54	60			
3	56	20			
3	58	5			
5	76	6			
	84	9			
6	106	11			
7,8	just grazed edge - v. small both missed				
9	168	25			
10	170	18			
11,12	186	19	18		
12	188	8			
13	196	39			
14	220	8			
15	240	11			
16	260	9			
16	270	29			
17	306	11			
18	308	20			
19	310	29			
20	312	10			
20,21	316	11	29		

7. Lustre

The property of lustre is related to measurable physical properties such as refractive index, flatness (macroscopic and microscopic) and hardness (ability to take a polish). In a gem and pearl context, lustre is a difficult parameter to quantify, but at the same time it is obviously very commercially important.

In the gemstone context, there are a number of descriptive terms that are used to indicate the type of lustre, viz

metallic	-	(metals)
adamantine	-	(diamond, etc)
vitreous	-	(glasslike)
resinous	-	(amber)
waxy	-	(eg turquoise, opal, jadeite)
greasy	-	(nephrite)
pearly	-	(pearl and moonstone)
silky	-	(satin-like)

The term *silky* is applied to gemstones with many needle like inclusions on the surface. So lustre is related to both surface and sub surface structure.

Sheen is a related term indicating the idea of light reflected from beneath the surface of a stone. Such terms as opalescence and silky or pearly reflection as shown by common opal are a result of the effect of the light reflecting from thin layers in the internal structure of the stone. In the final analysis, it is really the chemical composition and atomic structure of the gem which actually determines lustre. (references: Read, Gemmological Instruments, Newnes-Butterworth, 1978, and Liddicoat, Handbook of Gem Identification, Gemmological Institute of America, 1981).

Lustre instruments of reasonably primitive nature are sometimes used for diamond identification, measuring specular reflection from polished diamond facets. These are of little use for pearl due to the different nature of the lustre related to both surface and near sub surface properties, the opacity and the spherical shape. In addition, although there are large differences in lustre between high quality pearls and dull susa dama pearl, the real difficulty lies in the subtle gradations of quality as seen by the expert grader.

Having participated in the grading process of a couple of Broome operations, and attempted to extract by example a quantitative procedure, it appeared to the writer logical to use the property of image formation in a strong illumination field by reflection. This was done by holding a pearl in a position where, even with distortion due to the spherical mirror effect, one can view distant objects by reflection in the pearl surface. This procedure was then checked by endeavouring to produce demonstration of visual grading acceptable to the expert graders participating in the tests.

Two practical methods were then tried to produce an automatic lustre reading using the above principle. Both had the common link of the measurement of image quality (sharpness) using the imaging tools at hand in the Global Lab Image software. These approaches were applied to only a limited number of pearls to illustrate the type of results that may be achieved. Lack of time and

insufficient range of samples selected for lustre variations made a systematic evaluation difficult, however eventual applicability will depend on industry feedback.

7.1 Contrast Histograms

Initially we captured the reflected image of a light/dark grid pattern, which, if ideally specularly reflected from a metallic surface would have brightness values of essentially only two levels, high (being the brightness of the source of light) and low (dark). The GLI program was then used to produce a brightness histogram of the image. The ideal reflector would have two tightly clustered lobes, one for white (light source) and the other dark, with virtually no intermediate grey values. With a dull surface these lobes would be blurred towards a continuous distribution of grey values.

Typical such histograms are shown for high and low lustre pearls in fig 15.

7.2 Contrast Measurement Method

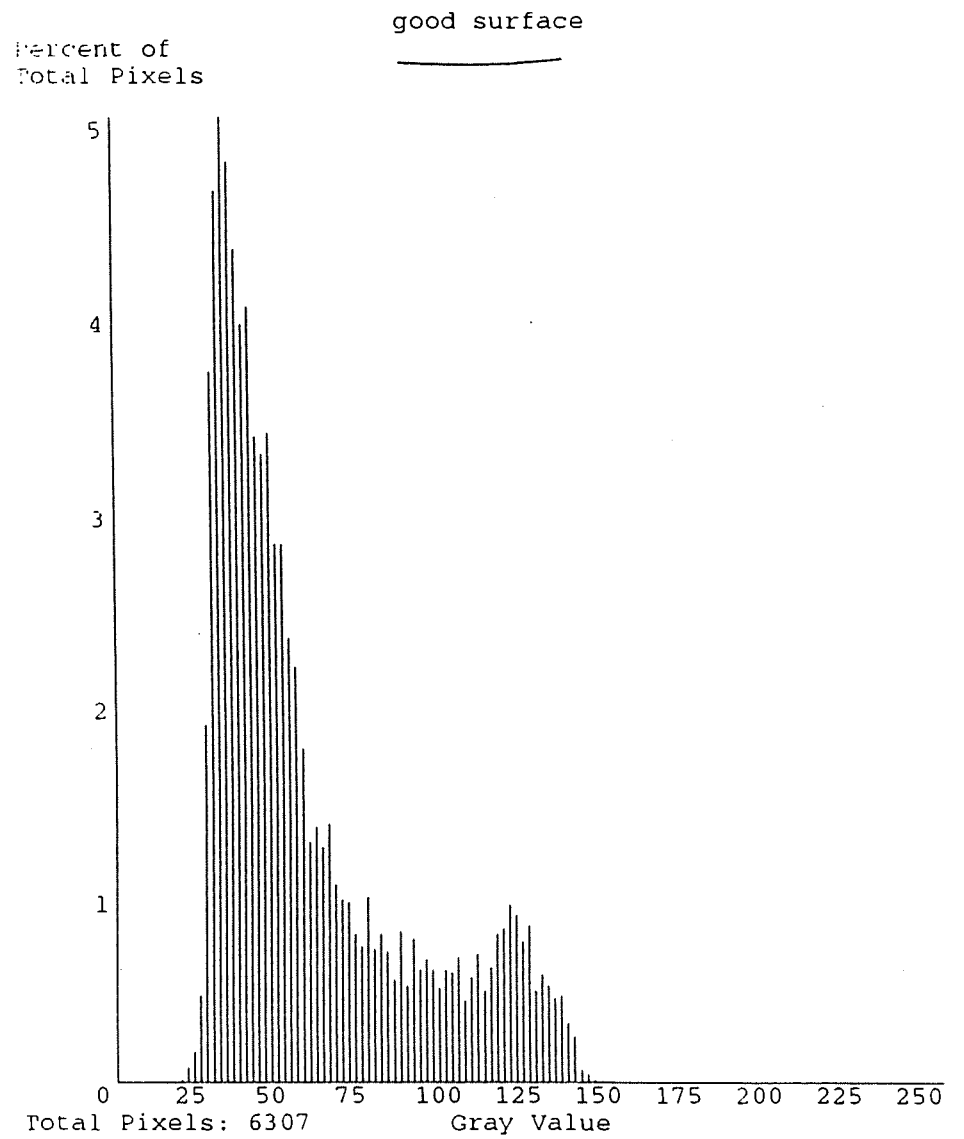
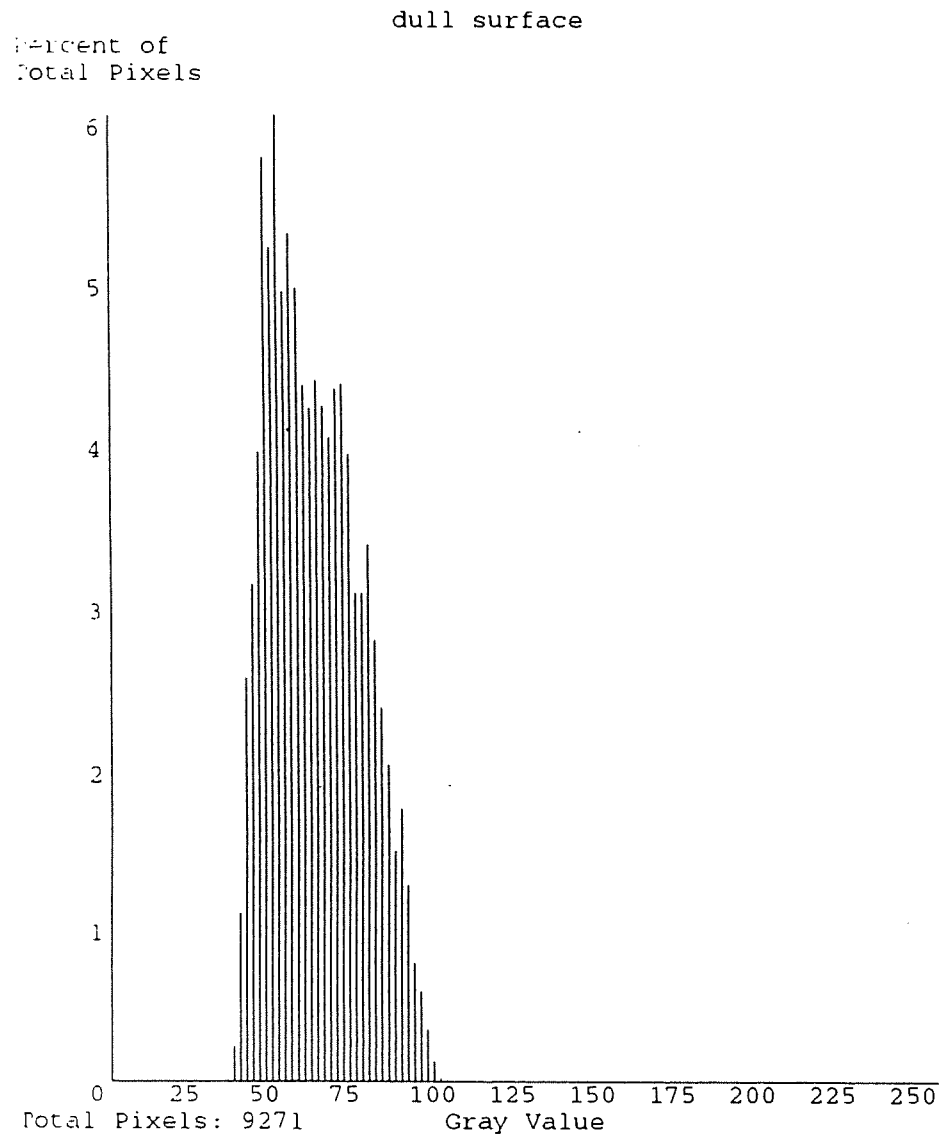
It was initially intended to use the above histograms to form quantifiable lustre numbers for each pearl via neural network or fuzzy logic procedures. The fuzzy logic analysing system available to us proved unduly complex and unsuitable, and a simpler procedure was formulated, following the optical set-up used with the above flaw measurement rig.

Essentially this again used the spherical mirror concept, but with a light/dark/light target reflected off the pearl surface. Example images are shown in fig 16. The GLI program was then used to extract a peak-to-valley ratio from a line brightness profile across these regions of the captured image.

Examples of such brightness line profiles of a stainless steel ball bearing (ideal metallic reflector), two good quality round pearls and a completely dull pearl from a bag labelled "Roebuck Bay Recoverables" are shown in fig 16.

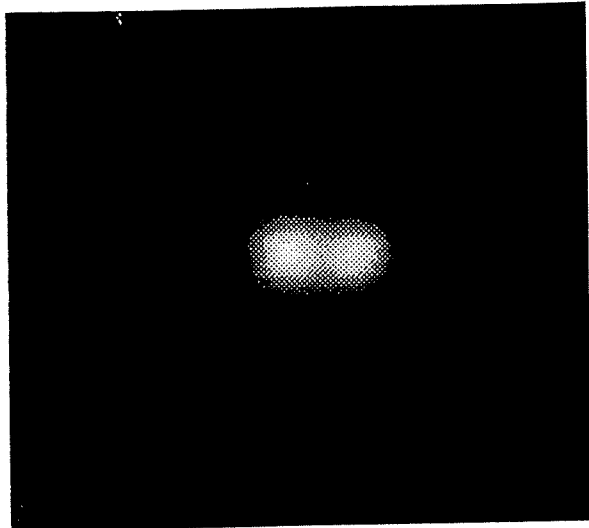
In order to extract a single lustre index, a simple arithmetic rule was applied to line profile readings as shown in fig 17 and table in fig 18. The table shows the lustre index being very high for the ball bearing, intermediate for the two high quality round pearls (with very little difference between the grade 1 AS1 and grade 4 AS4 examples) to very low for the dull pearl. The numerical results were extracted by averaging the lustre index taken over 6 regions of the surface of each example.

The routine so far has been only partially automated, although it is not anticipated that a fully automatic routine would be difficult to set up. All samples sent over specifically for this project were of high lustre, so the routine hasn't been systematically explored in the mid-quality lustre region.

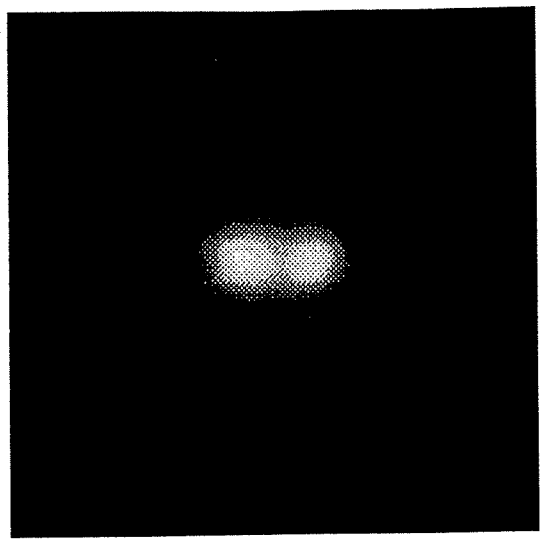


Lustre Histograms

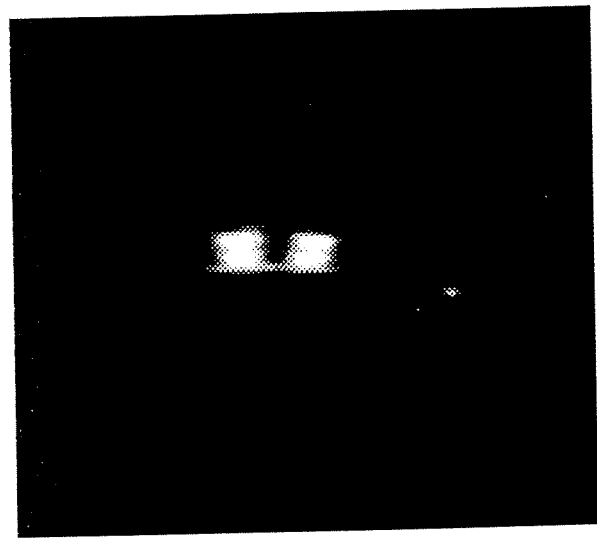
Fig. 15



AS1 Round Grade 1



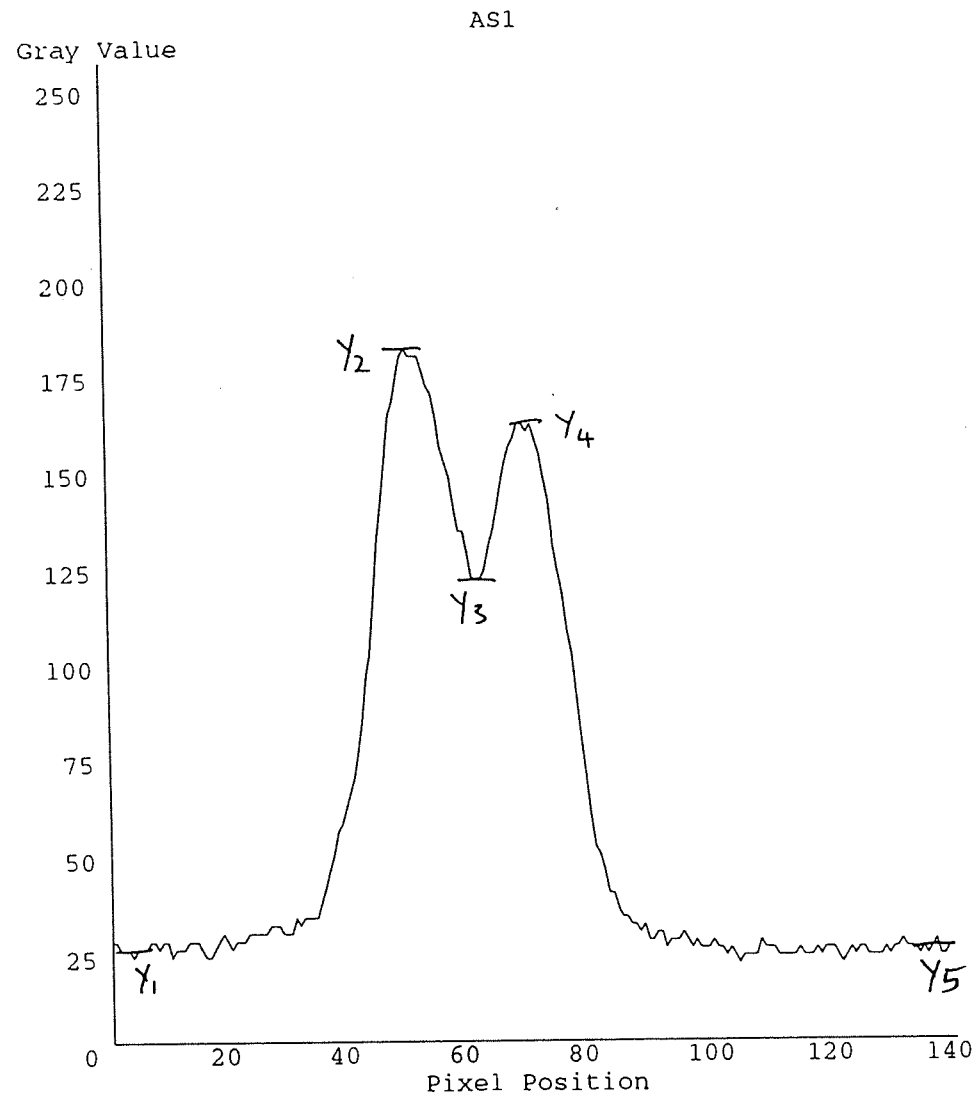
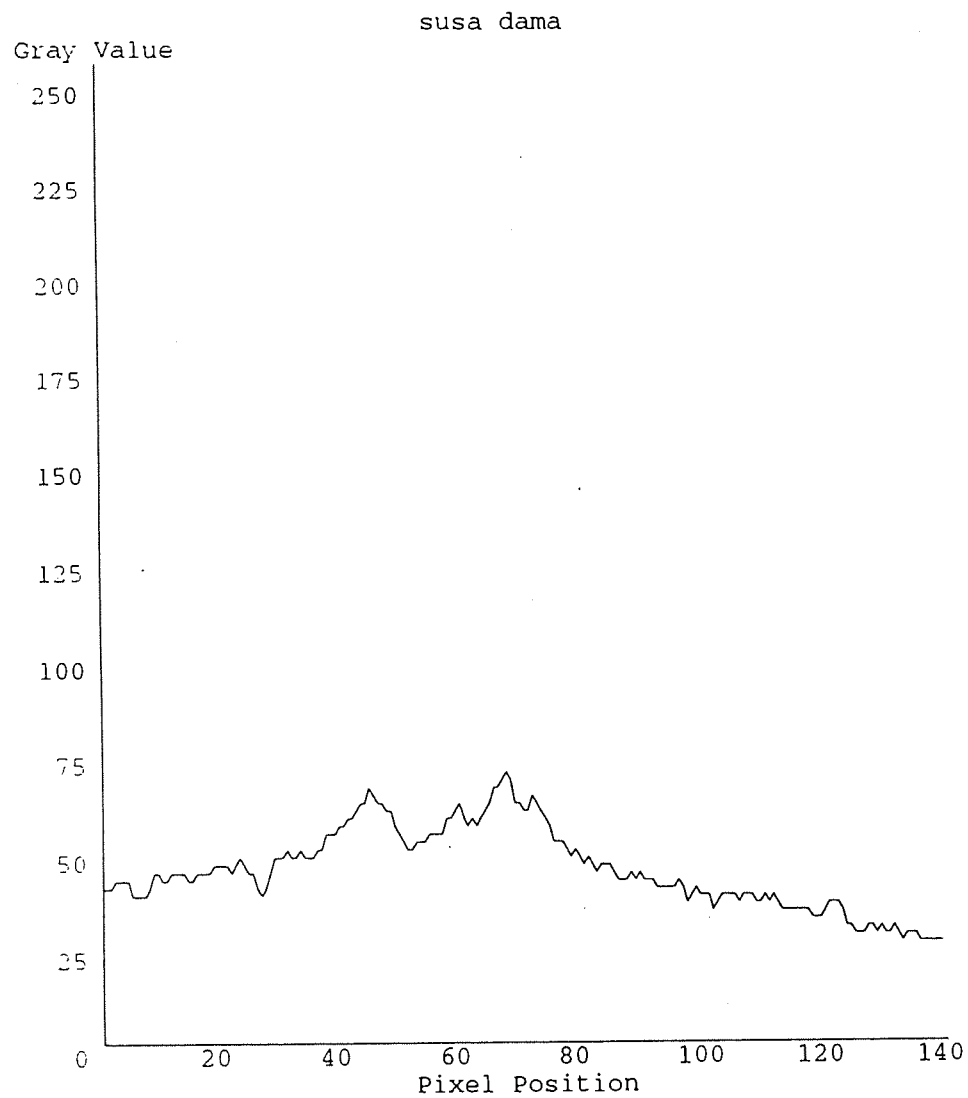
AS4 Round Grade 4



Ball Bearing



Roebuck Bay
Recoverable Rejeet



Line Profiles for Lustre Measurement

Lustre Measurement											
Pearl	Description	y1 (min1)	y2 (max1)	y3(min2)	y4(max2)	y5(min2)	Lustre Function, LF				
							{ y1-y2 + y2-y3 + y3-y4 + y4-y5 }				LF
AS 1	Round Grade 1	22	180	120	160	20	158	60	40	140	398
AS 4	Round Grade 4	25	181	130	176	23	156	51	46	153	406
RBRR	Roebuck Bay	40	66	52	70	26	26	14	18	44	102
	Recoverable Reject										
BB	Ball Bearing	24	254	40	254	30	230	214	214	224	882

Fig. 18

8. Colour Measurement

A significant precursor to pearl classification attempts has been the development of high speed colour diamond classifiers for Argyle Diamond Mines. The machines use light integrating spheres for optical inspection stations, extracting colour spectral measurements in the visible spectrum at rates around 10 per second. The computer system receiving the spectral information allowed for the teaching of sample colour spectra to the machine memory. This information was then able to be used to best match the unknown diamonds in production to the taught categories. Twelve physical outlet categories were available to place production categories.

In practice, this probably turned out to be one of the most difficult of the set of 5 measurements, due to the spherical mirror-like action of the continually curved surface similar to a spherical mirror. Special care had to be taken to avoid measuring the direct (specular) reflection from the pearl of the light surface.

8.1 Imaging Measurement of Colour

The initial measurement system for pearls incorporated an integrating sphere diffusing the light illuminating the pearl, in an attempt to reduce effects of the spherical nature of the pearl surface. With the intention of using a common measurement station for colour and for the other four parameter measurements, the Data Translation HSI Colour Frame Grabber DT 2851 was used to process colour image information from the high quality Pulnix CCD video camera.

The measurement of colour on a shiny spherical surface requires special care. Direct light from the light source should not reflect to the detector, so care was taken to light the pearl as diffusely as possible. Colour readings were then taken by selecting the region of the pearl image in an annulus toward the outer edge of the pearl. By this means the worst of the mirror-like top surface (ie nearest the camera) was avoided.

The HSI (hue saturation and intensity) approach had the advantage that it returned "intensity-like" information on the three colour parameters, each parameter being able to be treated like a grey scale with the GLI imaging software. In this way, hue for example can be isolated and represented as a 256 level variable in the same way as grey scale in a monochrome image. In colour science, hue expresses the concept of rainbow colours, eg bluishness. Saturation is linked to the vividness of hue colours. Intensity corresponds to shades of grey.

Histograms of hue over the surface of the pearl can then be computed by GLI (or tas in this case by the supplied application software with the HSI frame grabber), and patterns matched by a classification routine.

Limited results were obtained due to the presence of only a few colour samples in the batch sent for testing. Numbers for HS&I were between 0 and 255. The summary results were

	White	Blue/grey	Yellow
Hue	180	178	200
Saturation	45	49	32
Intensity	110	110	95

A more detailed table of these results is shown in fig 19. The suggestion from this is that yellow is the only colour safely able to be separated by this method.

8.2 Fibre Optic Probe

Because of the difficulty of controlling the specular pattern of light reflecting from the spherical surface of the pearl, the above technique had only moderate success in classifying pearls by colour. It certainly didn't show encouragement toward the subtler shades mentioned by one expert grader. The specular reflection results in transferring essentially the colour of the light source to the light receiver (human eye or TV camera), whereas the diffuse reflection is the one with the colour information about the surface under inspection. During the last phase of measurement taking for the project, an alternative colour analysis system was briefly set up, and evaluated on the same 2 colour-identified samples as above. The apparatus is shown in fig. 22.

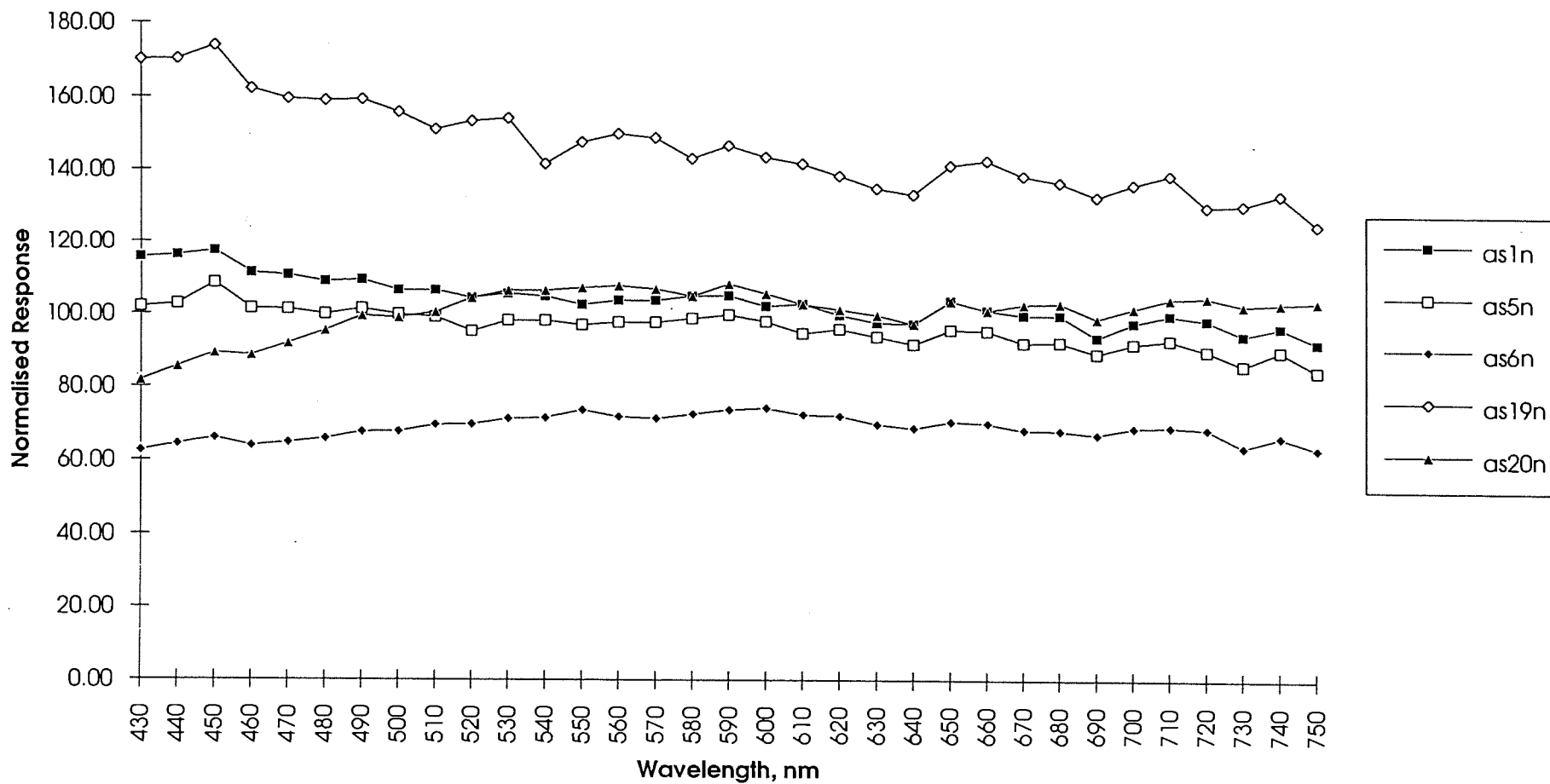
A bifurcated optical fibre probe station was set up, with combined (single) end positioned a few mm from the pearl surface (diameter of this end was approx 5mm). One of the separate ends was used as the illumination source (taking light from a stabilised quartz iodine lamp to the pearl surface). The other took reflected light from the pearl surface back to the input of an Oriel monochromator. A photomultiplier was coupled to the output of the monochromator and its response levels read for 10nm wavelength increments from 430 to 730nm.

The spectrum of a plain white card was used as a reference. The monochromator was a manual type, so each pearl took a considerable time to measure, having to read each 10 nm wavelength, and then compute normalised response. In fact a double normalising was applied, once with the white card to get a uniform system response, the again to make each spectrum refer to a 100 level at 430nm.

From graphs of figs 20 and 21, (one with one degree of normalisation, but showing level shifts, the other with those level shifts flattened out), although no formal quantification procedure was adopted, the resulting spectra for yellow, blue, blue/grey and white describe pearls showed some promise of displaying useful classification characteristics. However further quantitative work is needed to see whether the blue from white difference can be reliably picked up. Nevertheless uniformity of response appears to be better than for the imaging method, and as such the fibre optic station could be well integrated into a practical equipment sorting on colour, size and shape at least as a preliminary tool to assist grading.

Colour Measurements					
Colour	Pearl	Description	Hue Mean (Std Dev'n)	Saturation Mean (Std Dev'n)	Intensity Mean (Std Dev'n)
White	AS 1	Round Grade 1	179.00 (8.0)	47.40 (16.0)	113.30 (10.0)
	AS 2	Round Grade 2	180.40 (8.5)	44.60 (15.0)	115.90 (10.0)
	AS 3	Round Grade 3	178.60 (10.6)	39.30 (14.7)	120.60 (12.4)
	AS 4	Round Grade 4	178.80 (9.0)	39.60 (13.0)	116.40 (10.2)
Blue/grey	AS 5	Round Blue/grey	177.96 (7.70)	48.69 (16.0)	112.32 (12.0)
	AS 11	Button Blue/grey	178.30 (8.4)	49.20 (16.8)	107.10 (13.6)
Blue	AS 19	Circle Blue	178.00 (7.9)	53.70 (18.8)	108.00 (14.7)
Yellow	AS 6	Round Yellow	198.50 (22.9)	32.66 (16.6)	100.14 (11.8)
	AS 20	Circle Yellow	203.60 (47.0)	34.50 (18.0)	88.00 (10.0)

Pearl Spectral Data



Pearl Spectra, Normalised

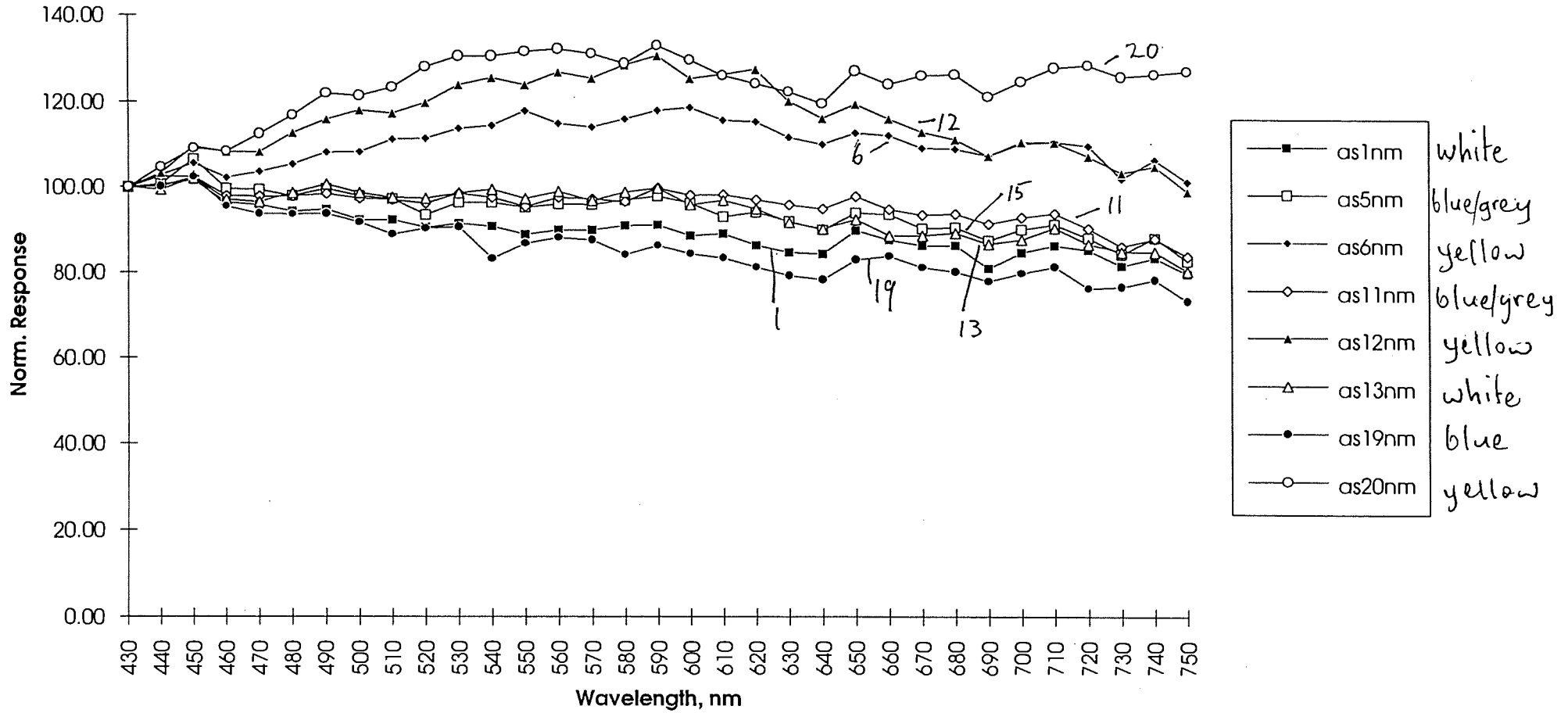
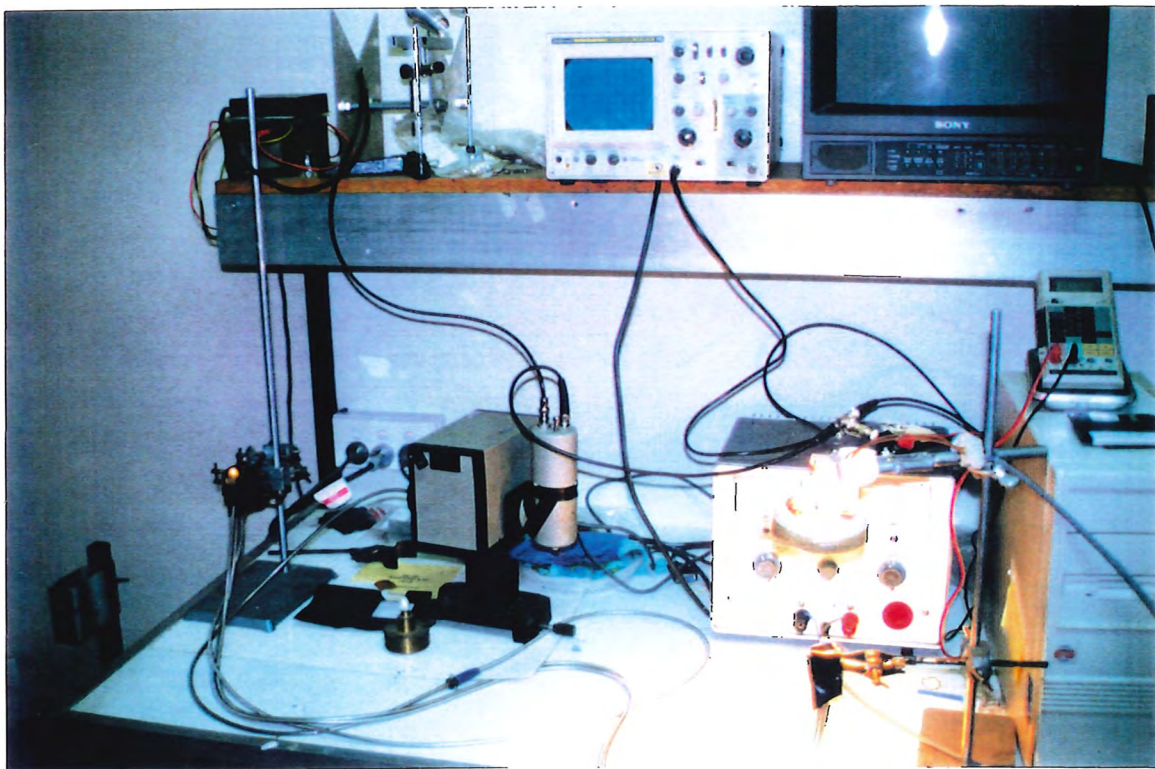


Fig. 21



Fibre Optic Probe Equipment for Colour Measurement

(showing on bench from left, pearl seated on brass spacer, bifurcated optical fibre, monochromator with photomultiplier attached, and QI light source with high current DC power supply, with oscilloscope above for output voltage measurement)

The colour measurement with a simultaneous spectrometer is rapid, with potential measurement rates of about 100 per second possible. A classification routine would need to be produced - this could be similar to the above described shape classifier system with the spherical harmonic values of the shape routine being replaced by wavelength series. Alternatively the spectra could be mathematically converted into x,y chromaticity coordinates which, as in the diamond classifier system development, could be used to describe like regions of pearl colour response.

The fibre probe system could be realised in a way the pearl is being rotated whilst the spectrum is being measured, thus averaging the colour over more of the pearl's surface.

Peter Hawkins
15th May, 1995

Appendix 1

An algorithm for object shape classification. *An interim report for Applied Sorting Pty Ltd*

K.A.Nugent
K.A.Nugent Consulting Pty Ltd
&
Professor of Physics, The University of Melbourne

Aim.

The aim of this report is to propose and describe a simple and computationally efficient approach to determining the shape of opaque objects, such as pearls.

General approach.

In discussion with Peter Hawkins of Applied Sorting, the intent of this part of the pearl classification project is to find some way of rapidly acquiring shape data and matching it to accepted shape classifications.

The approach proposed here is to observe the shadow of the object as it is rotated on a turntable, or equivalent, and to use some form of processing related to tomographic imaging to deduce its shape. Conventional tomographic imaging is far too computationally intensive to perform on this problem. On the other hand, full volumetric information is neither desired nor available. Thus, I propose here an algorithm that is loosely based on tomographic ideas and which is able to determine the surface shape of the object.

Surface algorithm.

1. *The principle:* Consider first the two-dimensional problem. A projection in a direction specified by θ is shown below.

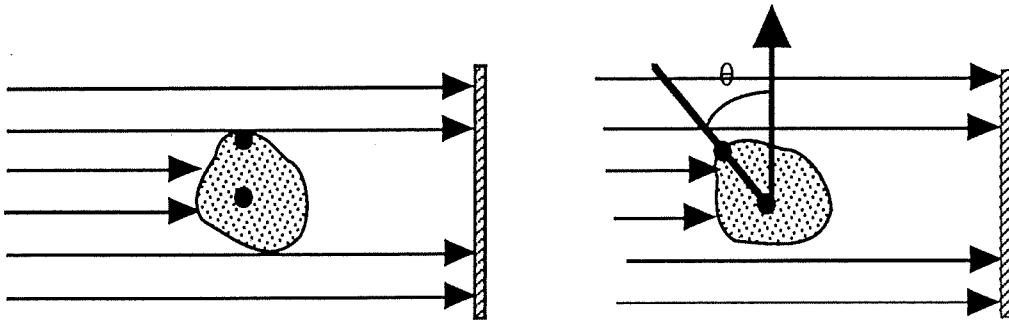


Figure 1: The object is illuminated and the shadow is recorded for a number of object orientations

The object casts a shadow describing the projection of the surface of the object onto the detector. The detector sees areas that are either illuminated or they are not. Further, given the object is a contiguous solid, there will be a well

defined boundary separating illuminated regions from those which are not. That is, for the 2D problem, the projection may be fully described by the shadow boundary which is only two numbers in this case. These we denote as X_1 and X_2 in the figure below.

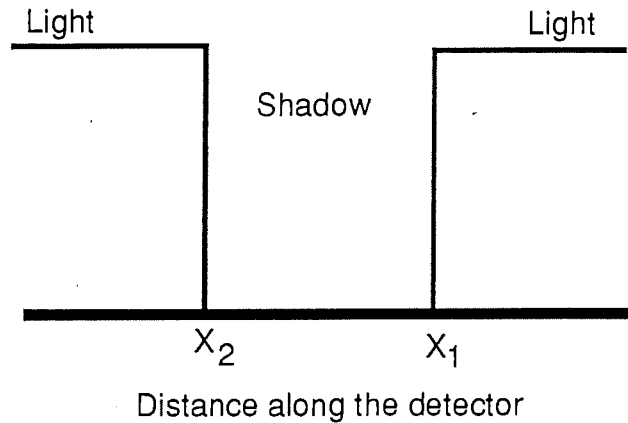


Figure 2: A 1D shadow recorded by the detector. The information in this shadow is fully specified through its boundaries X_1 and X_2 .

We acquire these numbers X_1 and X_2 for each projection obtained and we denote the projection as 1 in the illuminated region and 0 in the shadow region. To reconstruct the boundary, we set up a 2D array (the "image") containing '0's. Each projection is "backprojected", that is the observed data is smeared back along its direction of projection, as shown below, such that if the image points are converted to '1' if the backprojection is '1' and is left alone if the backprojection is a '0'.

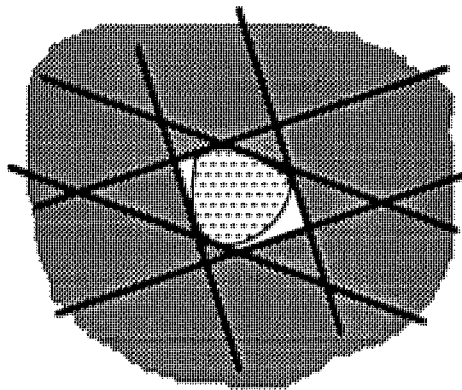


Figure 3: We describe a shadow such as in figure 1 as a 1 if illuminated and 0 if not. Backprojection consists of smearing this back over the object volume. In this figure we show the result of three backprojections for a 2D object. It can be seen that a reasonable representation of the object boundary is obtained.

For a sufficiently large number of backprojections, the area in the image containing '0's will be an excellent representation of the original opaque object. It will then be possible to use this data set to obtain the object boundary. It should be noted that the shadowing used by this approach will not allow the observation of hollows in the object: The algorithm will act to fill them in. I understand that this will not be an important drawback for the pearl classification project.

The principle outlined in preceding paragraphs applies equally well to the surface shape of three-dimensional opaque objects.

2. Implementation: For three-dimensional data sets, the approach described above will work but will ^{ve}acquire the retention of a three-dimensional data set in order to determine the surface shape. This imposed rather stringent requirements on data storage in the processing computer. With modern personal computers this will probably not be too much of a problem but it is nevertheless desirable to obtain a more efficient use of computational resources.

Without going into details, it is possible to write out the above principle as a geometric process in which, by choosing an appropriate co-ordinate system, all the above processing can be performed by determining shadow boundaries in the 2D projections and using geometry to determine the 3D object boundary. The geometry to do this is straightforward but messy and will allow the concept described here to be done via a very simple algorithm without requiring three-dimensional data sets.

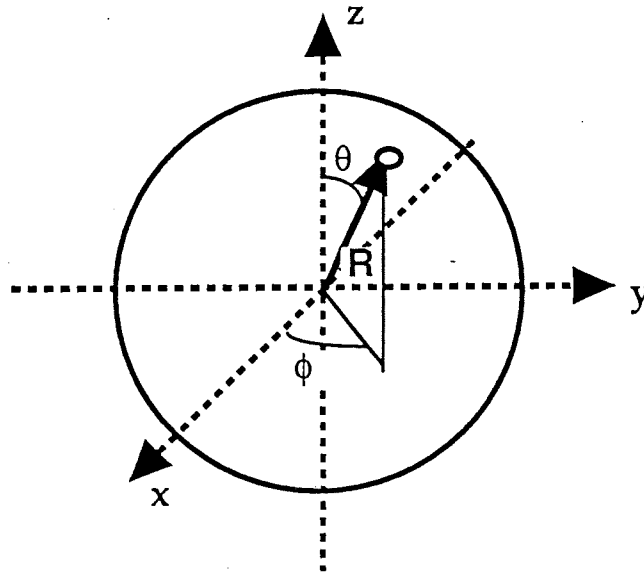
Summary

This report has described a simple and efficient approach that will allow the rapid determination of the surface of the three-dimensional opaque object. The surface information so obtained may then be subsequently used to determine which shape classification that it best meets. The discussion here indicates that it should be possible to directly determine the shape information required for classification to occur. It remains to be seen how many backprojections will be required in order to obtain an adequate boundary description .

Appendix 2

Shape Determination Using Spherical Harmonics

In the case of an object with approximately spherical symmetry, such as a pearl, one may describe the shape of the object using the function $R(\theta, \phi)$ which gives the radius of the pearl as a function of two angles.



Co-ordinates used to specify 'radius' as a function of the angles θ and ϕ .

This description does not characterize the pearl shape very clearly and there are advantages to writing the pearl shape as a series of spherical harmonics,

$$R(\theta, \phi) = \sum_{\ell=0}^p \sum_{m=-\ell}^{+\ell} A_{\ell}^m Y_{\ell}^m(\theta, \phi)$$

where the pearl shape is now fully determined by the numbers A_{ℓ}^m where ℓ runs from 1 up to highest number chosen (eight in the work so far) and m runs from $-\ell$ to $+\ell$. $Y_{\ell}^m(\theta, \phi)$ are the functions known as spherical harmonics. The numbers A_{ℓ}^m are entirely analogous to the frequency distribution obtained by Fourier analysis for one and two dimensional signals.

In this case, for example, a perfect sphere has $A_0^0 = R$, where R is the radius of the sphere, and all the other terms are zero. As the pearl deviates from purely spherical, other A 's become significant and the pattern of co-efficients excited is characteristic of the pearl shape. In this project, the aim is to determine the

coefficients corresponding to different pearl shapes so as to allow their shape to be determined.

The output of the fitting program, then, is a set of numbers of the following form, where we show numbers only up to $\ell=6$.

$$\begin{array}{cccccccc}
 & & & & & & & A_6^{+6} \\
 & & & & & & A_5^{+5} & A_6^{+5} \\
 & & & & & A_4^{+4} & A_5^{+4} & A_6^{+4} \\
 & & & A_3^{+3} & A_4^{+3} & A_5^{+3} & A_6^{+3} \\
 & & A_2^{+2} & A_3^{+2} & A_4^{+2} & A_5^{+2} & A_6^{+2} \\
 & A_1^{+1} & A_2^{+1} & A_3^{+1} & A_4^{+1} & A_5^{+1} & A_6^{+1} \\
 A_0^0 & A_1^0 & A_2^0 & A_3^0 & A_4^0 & A_5^0 & A_6^0 \\
 & A_1^{-1} & A_2^{-1} & A_3^{-1} & A_4^{-1} & A_5^{-1} & A_6^{-1} \\
 & & A_2^{-2} & A_3^{-2} & A_4^{-2} & A_5^{-2} & A_6^{-2} \\
 & & & A_3^{-3} & A_4^{-3} & A_5^{-3} & A_6^{-3} \\
 & & & & A_4^{-4} & A_5^{-4} & A_6^{-4} \\
 & & & & & A_5^{-5} & A_6^{-5} \\
 & & & & & & A_6^{-6} \\
 CL(1) & CL(2) & CL(3) & CL(4) & CL(5) & CL(6) & CL(7)
 \end{array}$$

This set of numbers acts as a unique fingerprint for the shape of the pearl.

For most purposes, there is more detail than is required in these numbers and so, in practice, they are compressed into two sets of seven (in the above example but nine are used in practice) numbers by adding along the rows and the columns, so that CL(1), CL(2) etc shown above are the sum of the squares of all the numbers above it. The data CJ(m) etc are the sums of squares for the rows for both plus and minus m.

Appendix 3

PSHAPE_1.XLS

Shape tests on Second Series							
Minimum Distance Classifier							
Pearl		Round	Drop	Button	Semi- Baroque	Circle	Decision
Round Group							
1		0.979	9.123	4.178	4.530	14.007	Round
2		1.358	9.181	4.262	4.200	13.963	Round
3		1.860	8.430	5.376	5.105	12.913	Round
4		1.005	9.150	4.608	4.931	14.162	Round
5		1.099	9.085	4.929	5.597	14.385	Round
6		1.414	7.982	3.878	3.795	13.041	Round
7		1.346	9.027	4.356	5.152	13.972	Round
8		1.642	7.556	4.276	4.163	12.601	Round
9		2.482	7.351	4.062	4.080	12.628	Round
10		1.327	7.405	4.620	4.508	12.527	Round
11		0.922	8.930	4.383	4.812	13.806	Round
12		1.156	8.441	5.075	4.896	13.462	Round
13		1.017	9.063	4.849	5.073	13.939	Round
14		0.980	9.242	4.663	4.952	14.117	Round
15		1.385	8.435	4.727	5.077	12.915	Round
16		0.740	9.168	4.659	4.964	14.156	Round
17		1.008	9.125	4.440	4.839	14.029	Round
18		2.367	6.858	4.302	2.981	11.969	Round
19		2.040	7.635	4.343	3.624	12.703	Round
20		1.388	8.300	4.925	4.908	13.158	Round
21		1.397	8.640	4.056	3.988	13.544	Round
22		1.802	9.603	5.067	5.765	14.491	Round
23		0.679	8.860	4.821	5.071	13.736	Round
24		1.020	9.164	4.488	5.243	14.133	Round
25		1.585	8.105	3.629	3.781	13.079	Round
26		1.403	9.333	4.059	4.418	14.097	Round
27		0.933	8.698	4.747	4.776	13.524	Round
28		1.830	7.688	4.223	3.363	12.597	Round
29		1.303	8.271	4.793	4.666	13.146	Round
30		1.405	9.549	4.466	4.799	14.322	Round
31		2.316	7.573	4.672	4.826	12.166	Round

PSHAPE_2.XLS

Shape tests on Second Series							
Minimum Distance Classifier							
Pearl		Round	Drop	Button	Semi- Baroque	Circle	Decision
Drop Group							
1		3.561	6.447	5.465	2.959	11.648	S-Baroque
2		16.269	9.216	17.961	15.589	6.121	Circle
3							
4		8.33	1.484	9.733	7.448	6.539	Drop
5		12.119	4.706	12.913	11.218	7.488	Drop
6		6.07	4.586	8.167	5.958	10.95	Drop
7		9.809	3.442	11.889	9.565	6.128	Drop
8		5.925	4.68	6.805	4.742	8.876	Drop
9		4.164	5.252	5.44	3.75	11.352	S-Baroque
10		6.441	4.611	7.264	4.547	10.253	S-Baroque
11		14.379	8.716	16.209	13.886	14.42	Drop
12		5.401	5.395	5.456	2.654	11.648	S-Baroque
13		9.593	7.16	11.362	9.038	13.365	Drop
14		16.223	9.788	18.234	15.91	15.297	Drop
15		12.38	6.433	13.517	10.993	5.269	Circle
16		14.103	6.347	13.37	11.675	6.576	Drop
17		7.108	3.689	6.732	4.941	8.792	Drop
18		14.78	6.159	15.089	13.394	2.588	Circle
19		6.568	6.474	5.499	8.069	11.177	Button
20		8.022	6.728	7.701	9.636	12.287	Drop
21		9.785	2.319	10.579	8.884	5.07	Drop
22		6.752	4.817	6.715	3.089	9.765	S-Baroque
23		9.955	2.962	10.471	7.736	5.268	Drop
24		11.332	4.093	9.632	6.586	6.817	Drop
25		6.799	5.715	6.637	2.349	10.636	S-Baroque
26		10.926	4.154	11.026	9.013	5.478	Drop
27		9.108	3.481	7.787	4.89	8.307	Drop
28		7.648	4.242	7.05	3.479	9.045	S-Baroque
29		7.033	6.319	6.326	2.138	11.084	S-Baroque
30		5.495	3.891	6.388	3.785	9.031	S-Baroque
31		9.383	1.303	9.684	7.989	5.889	Drop
32		7.892	2.316	7.629	5.613	8.183	Drop
33		5.593	4.452	5.806	3.483	10.141	S-Baroque
34		8.213	3.271	7.752	5.696	7.321	Drop
35		5.837	4.408	5.913	4.138	10.045	S-Baroque
36		7.668	3.773	7.45	5.516	9.3	Drop
37		4.397	4.845	4.913	3.162	10.122	S-Baroque
38		6.826	3.75	7.53	4.567	8.276	Drop
39		4.467	6.422	3.822	3.35	12.422	S-Baroque
40		4.102	5.566	5.087	3.728	11.676	S-Baroque

PSHAPE_2.XLS

41		3.556	6.172	4.456	2.769	11.3	S-Baroque
42		4.408	5.674	4.318	2.137	11.185	S-Baroque
43		3.578	6.046	3.807	3.376	12.146	S-Baroque
44		5.794	5.674	5.934	2.26	11.438	S-Baroque
45		5.407	5.321	5.108	3.413	10.62	S-Baroque
46		5.33	5.347	4.526	2.376	10.55	S-Baroque
47		4.409	5.952	4.294	1.707	11.092	S-Baroque
48		7.592	5.242	8.006	4.462	10.26	S-Baroque
49		4.951	5.919	5.055	2.024	10.684	S-Baroque
50		6.309	2.971	8.765	5.18	7.936	Drop

Shape tests on Second Series							
Minimum Distance Classifier							
Pearl		Round	Drop	Button	Semi- Baroque	Circle	Decision
Button Group							
1		6.083	6.298	4.293	7.154	11.778	Button
2		1.771	8.838	5.486	6.107	14.080	Round
3		2.878	10.389	7.221	7.347	14.546	Round
4		3.552	9.495	3.919	6.439	15.495	Round
5		1.892	9.033	2.824	5.239	14.050	Round
6		2.354	8.867	5.560	6.953	14.462	Round
7		7.400	5.521	6.809	8.923	11.184	Drop
8		6.941	7.888	9.037	7.179	14.252	Round
9		2.488	8.914	3.372	6.653	13.667	Round
10							
11		4.691	7.567	2.857	5.916	12.916	Button
12		7.591	8.512	5.898	5.714	13.321	Button
13		4.804	9.710	2.624	4.067	14.611	Button
14		6.619	8.544	2.923	5.650	13.685	Button
15		4.476	8.214	3.365	5.320	13.307	Button
16		2.231	8.838	2.826	6.209	14.250	Round
17		10.122	9.294	6.463	8.815	14.978	Button
18		5.521	9.703	3.710	5.332	14.604	Button
19		4.213	9.760	3.144	7.042	13.580	Button
20		5.232	9.663	3.346	4.535	14.615	Button
21		2.377	10.281	4.538	5.352	15.242	Round
22		4.405	11.514	5.570	9.216	14.727	Round
23		2.615	10.692	3.311	5.039	15.457	Round
24		3.423	9.963	4.292	4.278	14.712	Round
25		3.873	9.863	3.533	5.421	15.942	Button
26		2.900	9.375	3.664	6.086	15.190	Round
27		2.427	10.057	4.138	4.905	14.828	Round
28		5.283	10.999	2.732	5.048	16.237	Button
29		2.526	9.815	3.738	5.576	15.152	Round
30		3.266	9.078	4.367	3.870	13.441	Round

SB.

PSHAPE_4.XLS

Shape tests on Second Series							
Minimum Distance Classifier							
Pearl		Round	Drop	Button	Semi- Baroque	Circle	Decision
Semi-Baroque Group							
1		8.361	9.723	9.684	8.150	16.035	S-Baroque
2		6.939	4.181	8.663	6.183	9.852	Drop
3		1.803	8.905	5.548	5.482	13.818	Round
4		3.695	6.457	5.257	3.830	12.588	Round
5		2.522	9.726	6.750	6.489	14.909	Round
6		2.233	7.748	5.367	5.155	12.525	Round
7		5.978	7.692	7.792	6.009	12.064	Round
8		7.262	4.300	9.125	6.703	9.298	Drop
9		2.266	9.237	6.133	6.358	14.476	Round
10		6.217	10.512	8.330	8.989	14.859	Round
11		6.694	4.115	7.624	4.662	8.580	Drop
12		13.964	7.522	14.312	11.795	6.100	Circle
13		4.603	7.790	5.225	1.508	12.755	S-Baroque
14		4.970	5.178	6.720	4.708	10.527	S-Baroque
15		8.930	4.520	10.263	7.868	6.306	Drop
16		3.886	9.468	5.294	6.143	13.155	Round
17		3.020	6.160	5.096	3.583	10.810	Round
18		4.164	8.259	5.311	2.729	12.910	S-Baroque
19		3.722	11.868	6.720	5.683	16.853	Round
20		8.163	4.444	8.918	7.215	9.492	Drop
21		4.186	5.161	4.949	2.857	10.870	S-Baroque
22		5.974	6.156	4.298	6.979	11.087	Button
23		6.222	5.524	7.596	5.748	8.194	Drop
24		3.207	7.107	3.533	3.169	13.075	S-Baroque
25		4.649	10.984	6.961	5.942	17.091	Round
26		8.850	4.878	8.197	6.436	10.384	Drop
27		10.205	4.091	9.564	5.963	6.813	Drop
28		13.298	5.692	14.274	12.359	2.339	Circle
29		17.205	8.905	17.990	16.295	6.458	Circle
30		16.939	11.029	19.143	16.259	9.786	Circle
31		22.027	16.199	24.078	21.030	10.605	Circle
32		4.229	5.319	4.790	3.370	11.392	S-Baroque
33		3.397	7.383	5.039	3.374	12.148	S-Baroque
34		2.596	7.887	3.454	2.927	12.683	Round
35		2.204	9.165	4.030	3.634	14.525	Round
36		2.073	8.661	4.542	4.360	13.574	Round
37		1.750	7.956	4.035	5.002	12.860	Round
38		2.781	7.805	4.840	4.225	12.577	Round
39		1.252	8.849	4.057	4.453	13.810	Round
40		3.007	9.424	4.828	4.566	14.800	Round

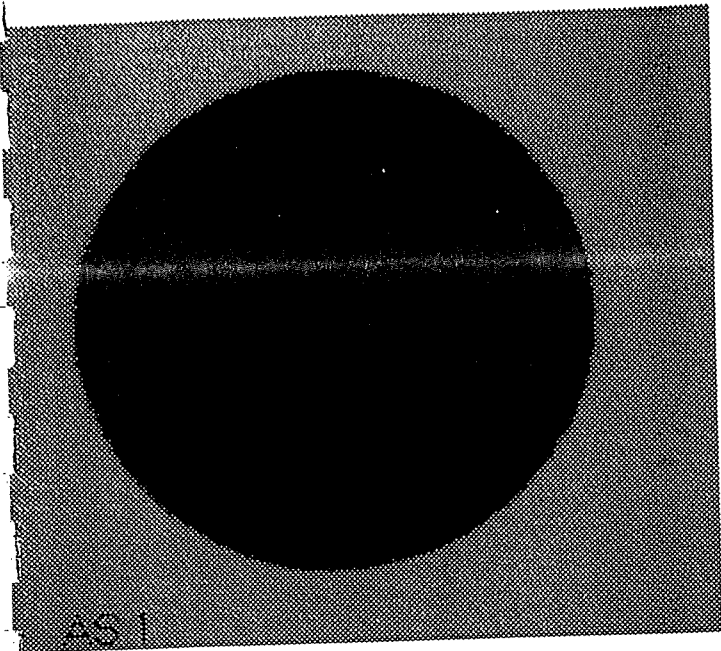
PSHAPE_4.XLS

41		1.583	8.302	4.064	3.610	13.252	Round
42		3.012	10.311	5.871	3.865	15.186	Round
43		3.468	5.715	4.548	2.740	10.635	S-Baroque
44		2.200	9.522	4.515	5.645	14.435	Round
45		2.699	9.070	4.534	4.397	15.091	Round
46		2.908	10.879	5.331	4.143	15.867	Round
47		2.516	8.987	4.753	6.568	15.246	Round
48		2.422	7.220	3.514	3.460	12.961	Round
49		2.496	7.878	3.707	2.878	12.989	Round
50		2.355	8.433	3.540	4.533	14.286	Round

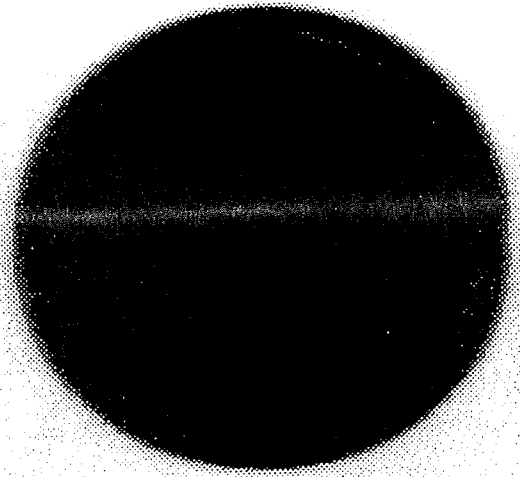
Shape tests on Second Series							
Minimum Distance Classifier							
Pearl		Round	Drop	Button	Semi- Baroque	Circle	Decision
Circle Group							
1		9.095	2.850	10.274	8.228	5.448	Drop
2		5.446	5.573	7.482	5.104	11.089	S-Baroque
3		11.250	5.634	13.735	10.478	5.549	Circle
4		8.226	4.412	10.410	7.011	6.994	Drop
5		2.837	6.339	4.323	2.866	11.385	Round
6		15.978	9.855	18.124	15.370	6.218	Circle
7		6.357	7.585	7.514	5.463	13.662	S-Baroque
8		8.220	2.032	8.813	6.895	6.107	Drop
9		14.770	6.625	15.930	14.232	4.350	Circle
10		6.707	5.988	7.477	7.501	9.319	Drop
11		18.581	12.066	18.442	14.922	10.200	Circle
12		10.243	4.190	10.861	8.537	9.761	Drop
13		2.706	10.822	3.081	5.143	15.873	Round
14		9.541	5.362	11.887	8.925	8.490	Drop
15		20.393	13.575	19.683	16.897	10.254	Circle
16		25.210	32.368	27.976	29.905	38.732	Round
17		19.576	11.910	18.214	15.669	9.764	Circle
18		11.005	7.184	12.243	10.651	10.645	Drop
19		15.617	8.285	17.159	14.835	4.759	Circle
20		17.080	8.844	17.850	16.155	4.252	Circle
21		21.626	13.363	22.637	20.942	8.568	Circle
22		16.280	8.086	17.171	15.476	5.056	Circle
23		13.611	7.430	15.496	13.162	2.987	Circle
24		16.495	8.232	17.364	15.669	3.933	Circle
25		11.418	3.250	11.915	10.135	4.833	Circle
26		13.847	6.364	14.270	12.281	2.531	Circle
27		30.609	24.166	30.883	28.491	22.212	Circle
28		8.845	2.187	9.853	7.422	5.185	Drop
29		9.285	4.663	10.040	8.340	7.415	Drop
30		11.474	5.309	12.457	9.971	5.181	Circle
31		13.732	5.227	14.043	12.348	2.998	Circle
32		11.425	4.456	12.666	10.507	2.593	Circle
33		10.834	2.487	11.729	10.034	4.088	Drop
34		9.030	2.586	10.073	7.328	5.494	Drop
35		9.485	6.800	10.728	9.249	8.612	Drop
36		11.660	4.859	11.377	8.594	8.324	Drop
37		5.103	4.306	6.443	4.417	10.053	Drop
38		6.613	3.712	6.343	4.525	9.061	Drop
39		5.040	11.488	6.014	8.160	13.745	Round
40		7.786	6.325	9.148	9.172	9.828	Drop

PSHAPE_5.XLS

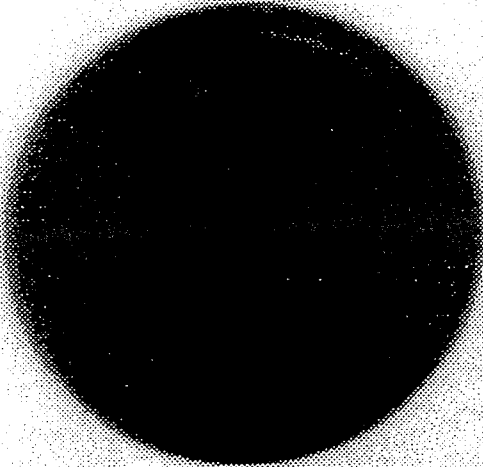
41		6.681	7.714	3.493	5.416	12.292	Button
42		4.799	5.154	7.045	4.979	10.564	Round
43		3.812	11.340	5.614	8.131	15.312	Round
44		4.602	8.784	3.074	7.403	14.805	Button
45		4.460	10.824	5.577	9.156	15.386	Round
46		2.397	6.998	4.167	5.164	12.791	Round
47		6.574	2.800	6.689	4.952	8.491	Drop
48		5.226	5.982	6.810	5.112	8.777	S-Baroque
49		4.922	10.317	3.813	6.369	14.805	Button
50							



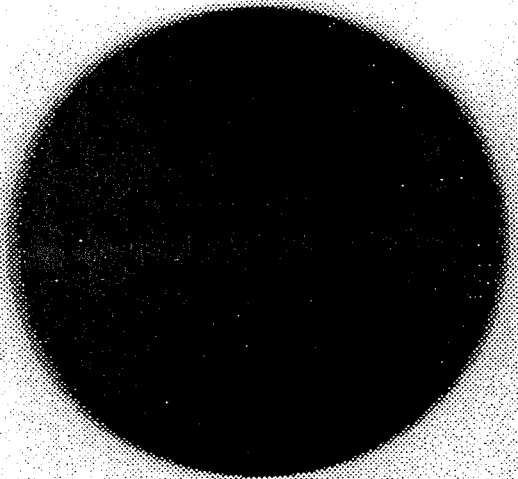
AS 1



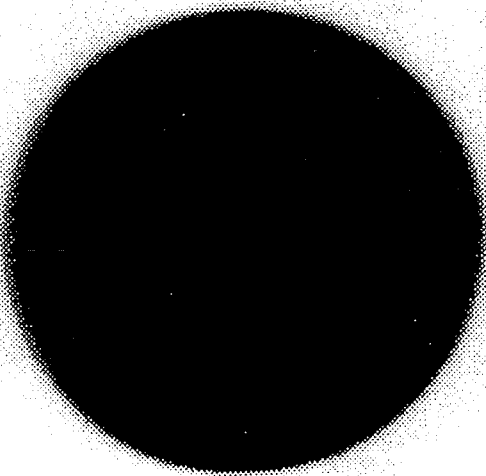
AS 2



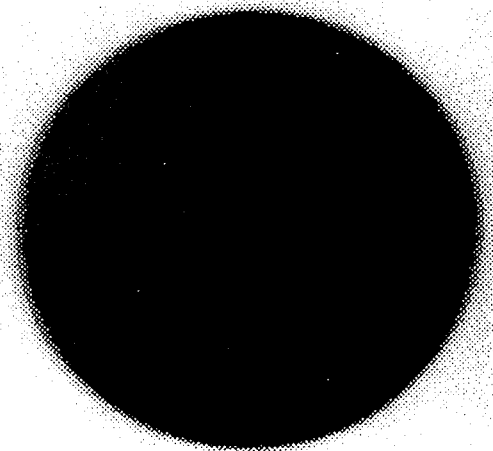
AS 3



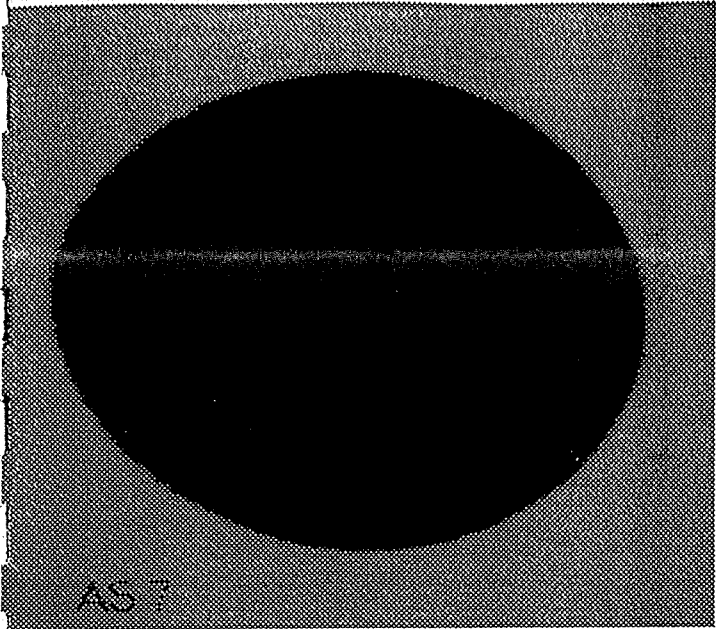
AS 4



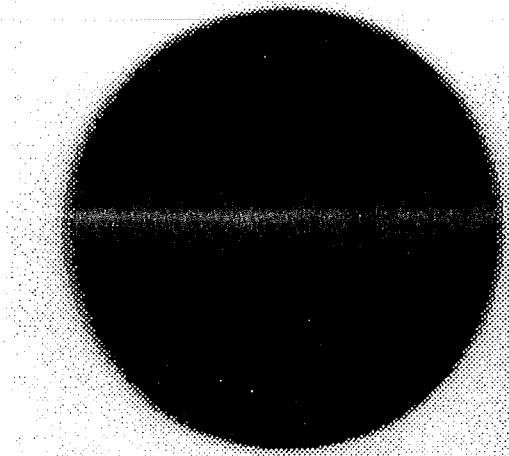
AS 5



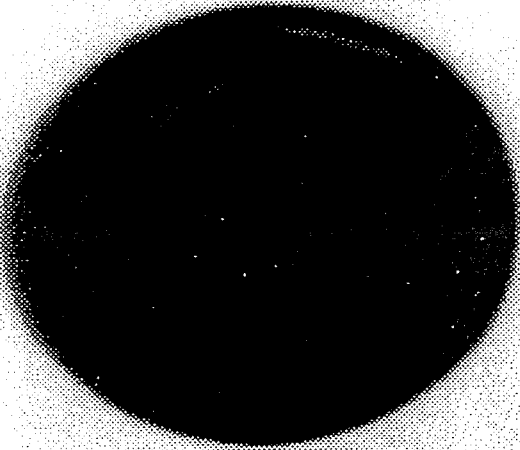
AS 6



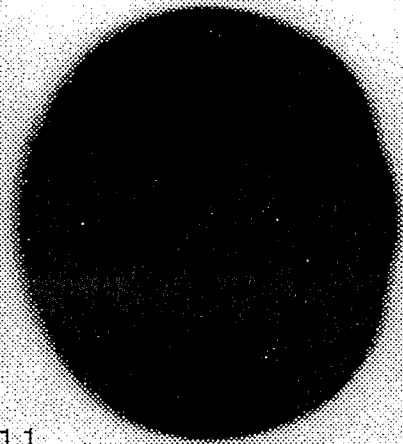
AS 7



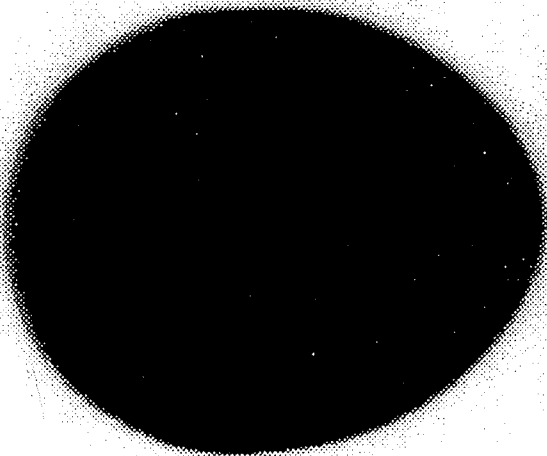
AS 10



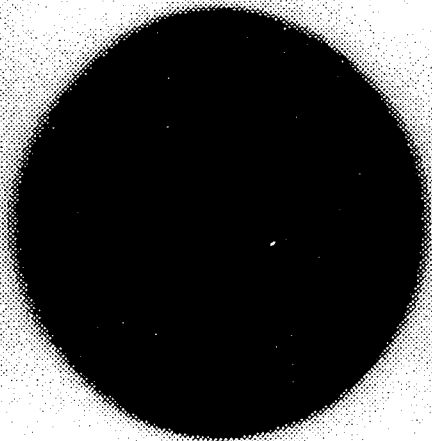
AS 8



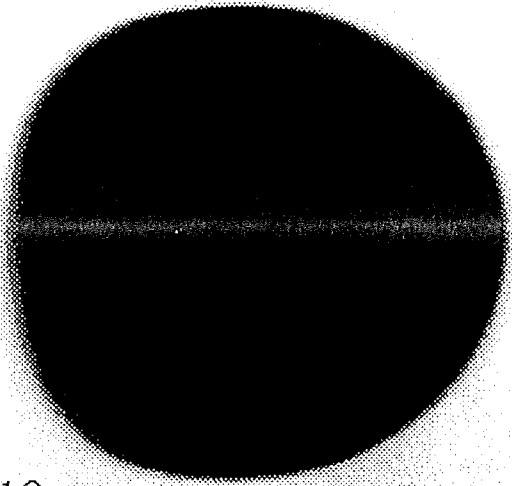
AS 11



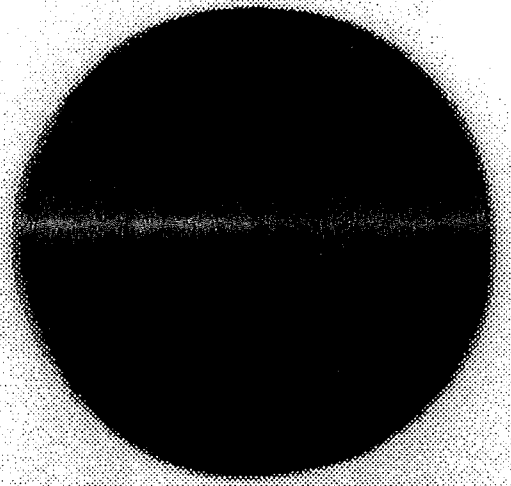
AS 9



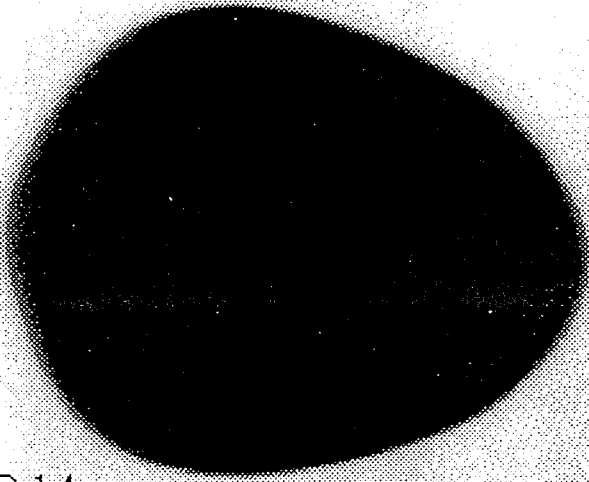
AS 12



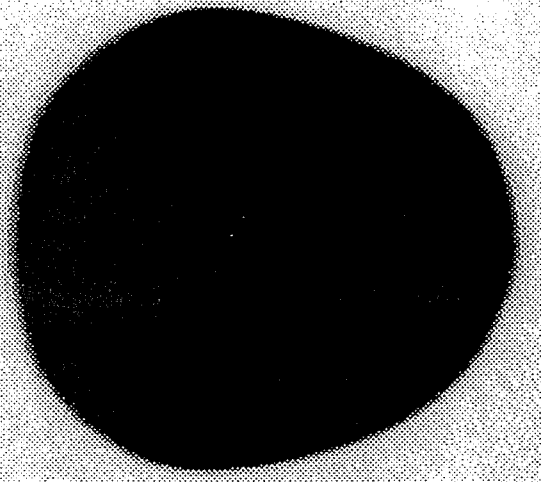
AS 13



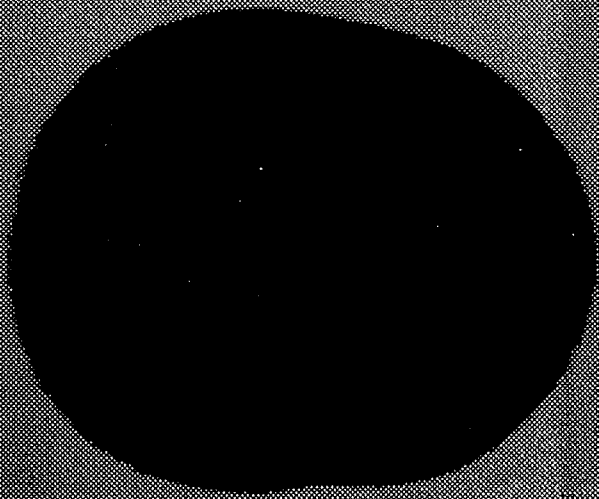
AS 16A



AS 14

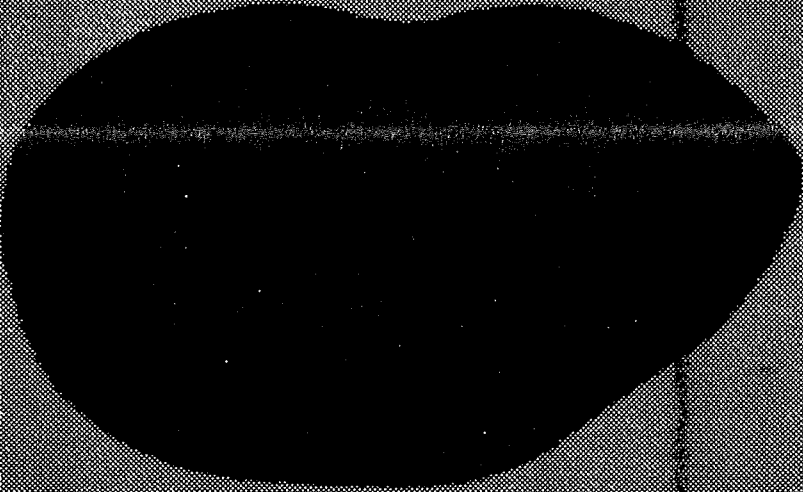


AS 16B

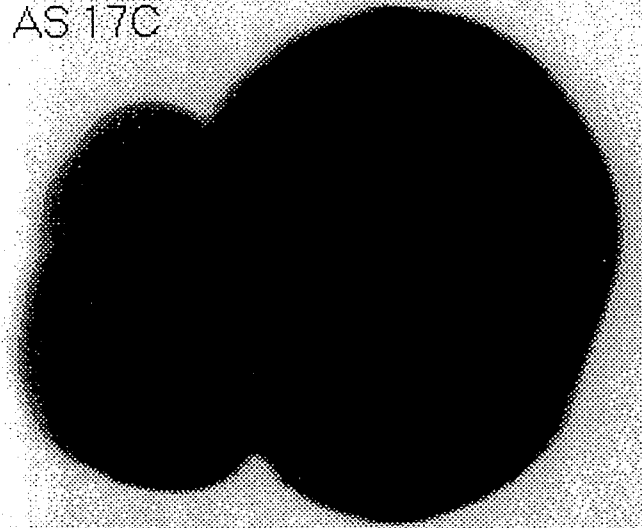


AS 15

AS 17



AS 17C

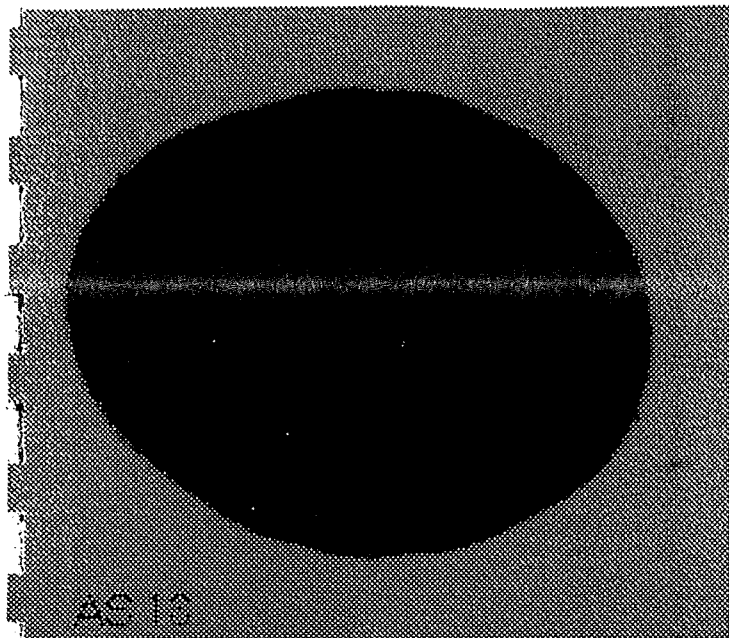


AS 17B

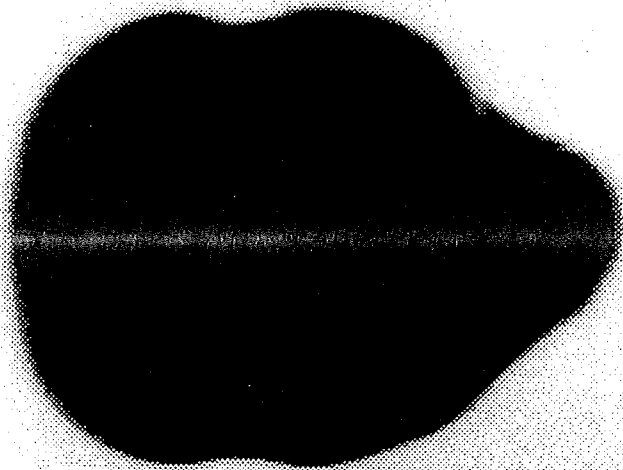


AS 17D

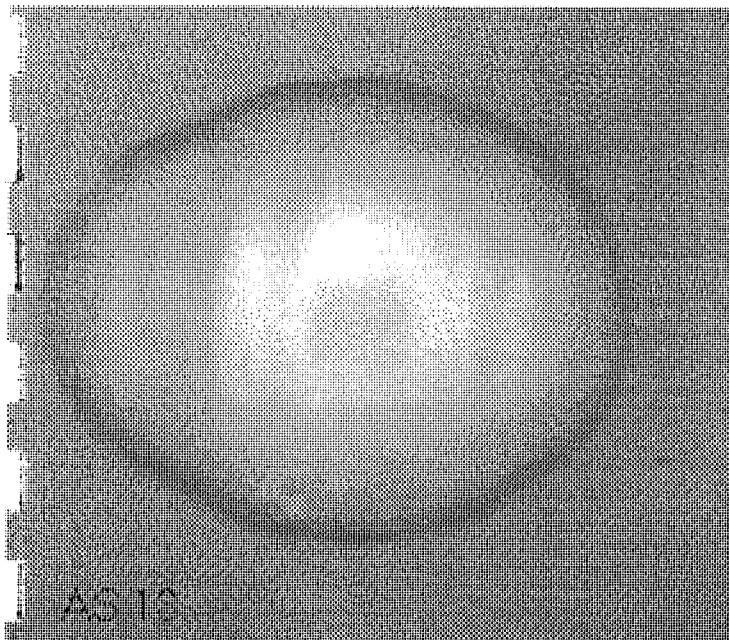




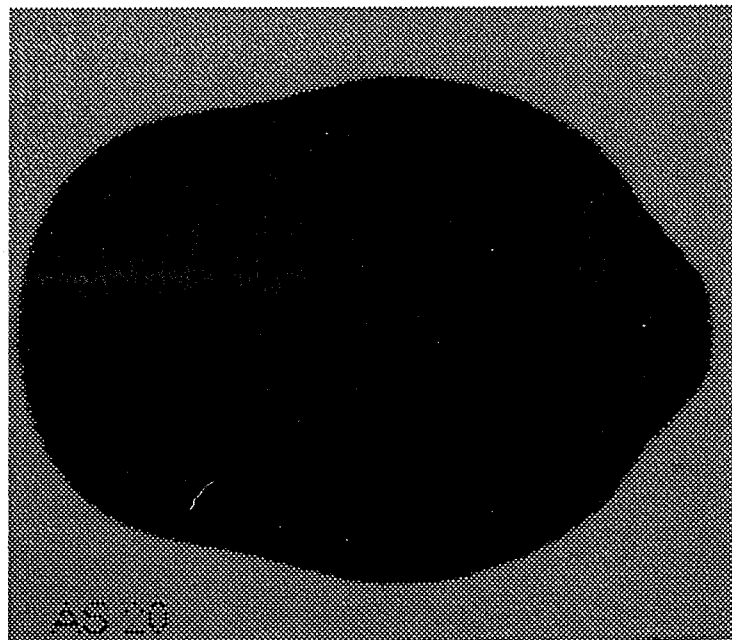
AS 18



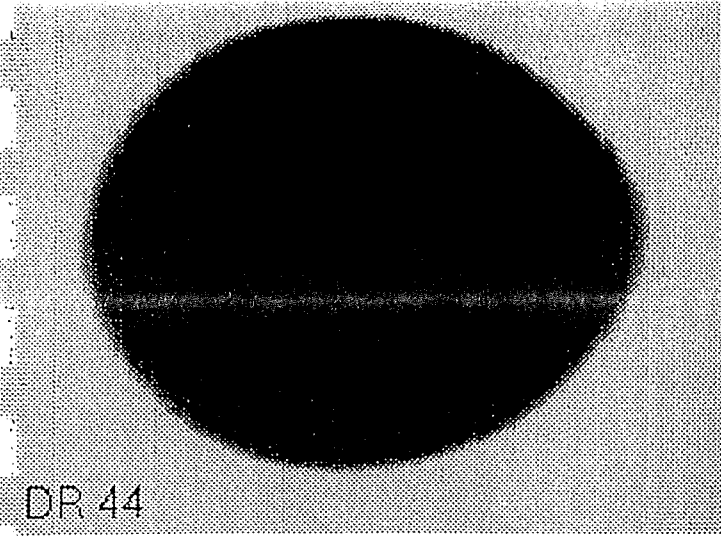
AS 19



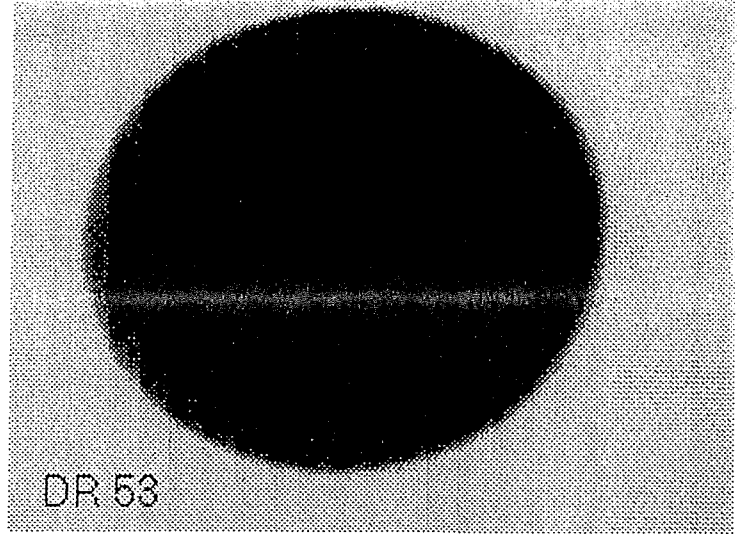
AS 18



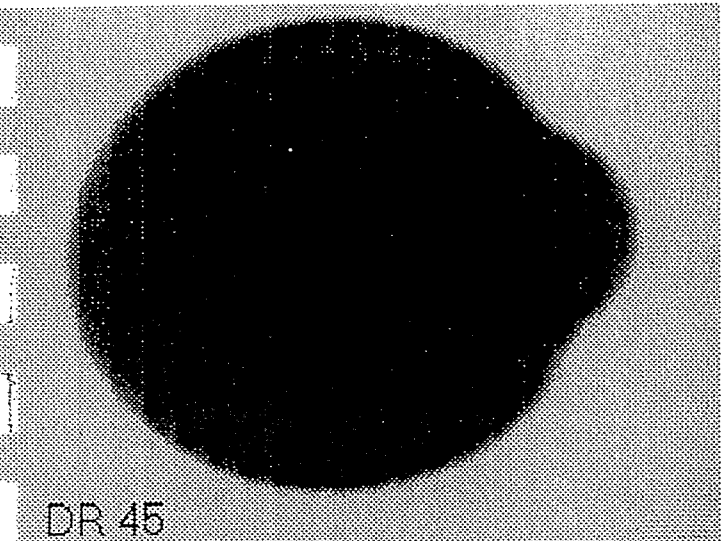
AS 18



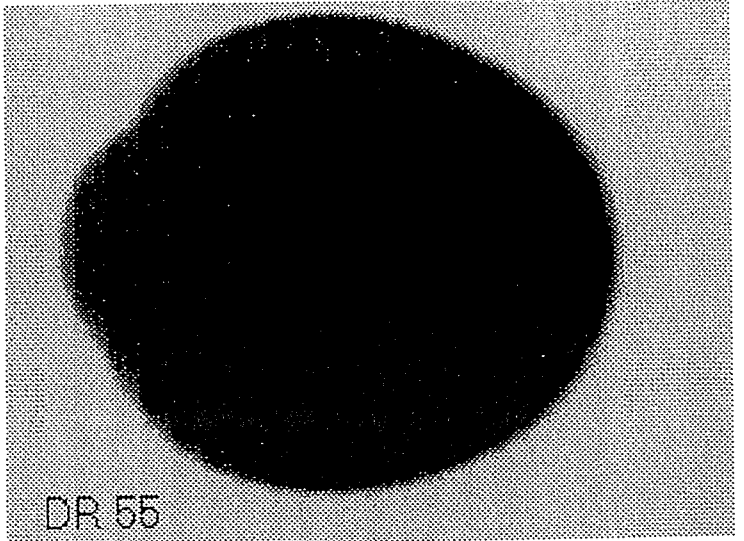
DR 44



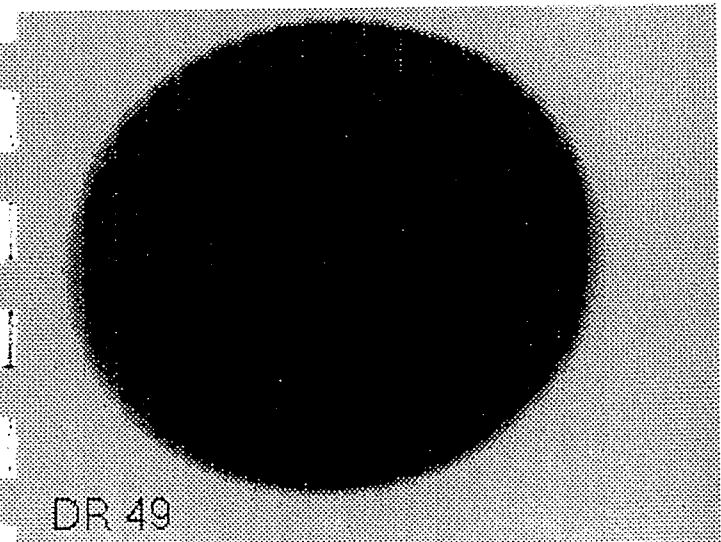
DR 53



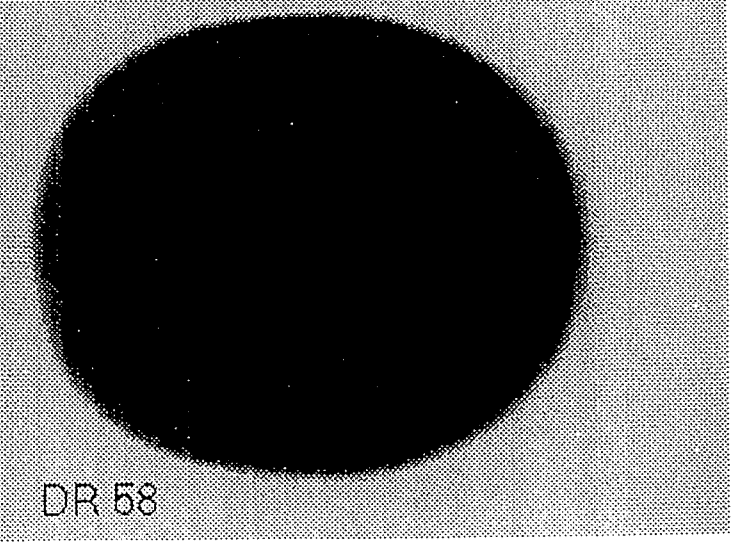
DR 45



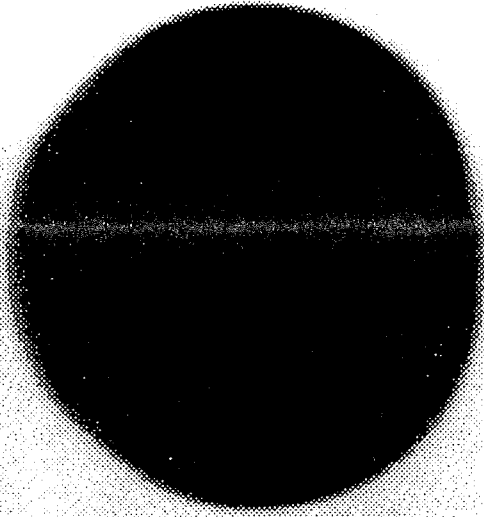
DR 55



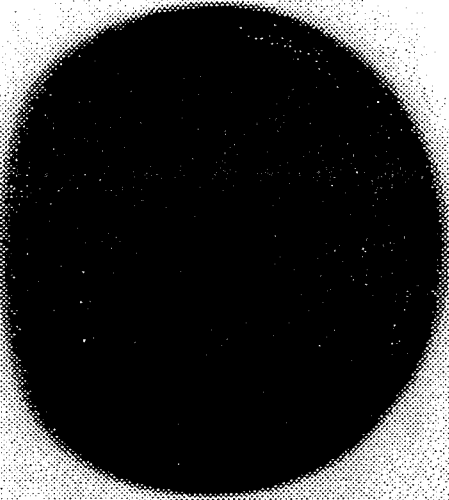
DR 49



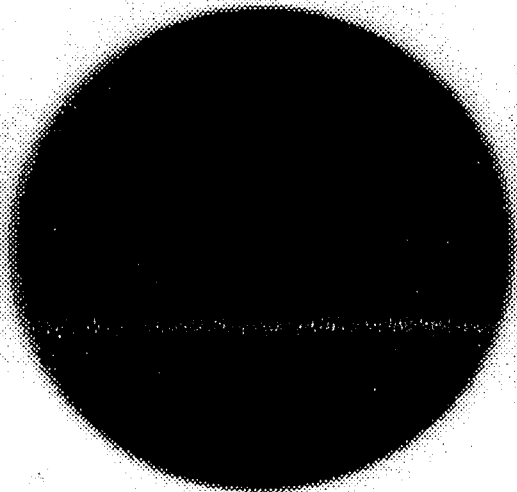
DR 58



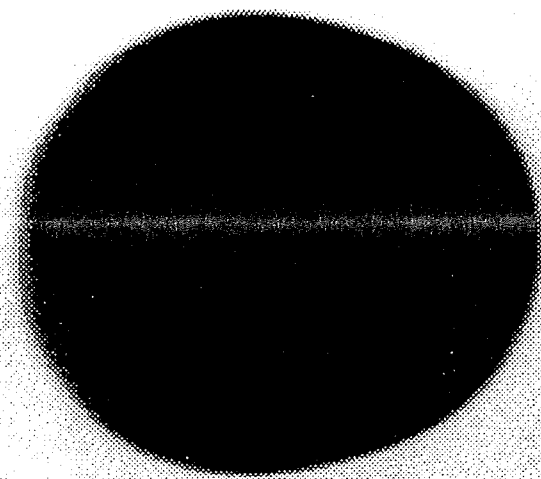
BU 11



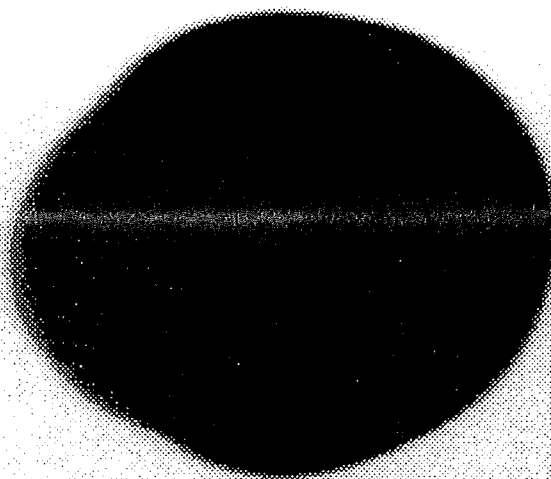
BU 12



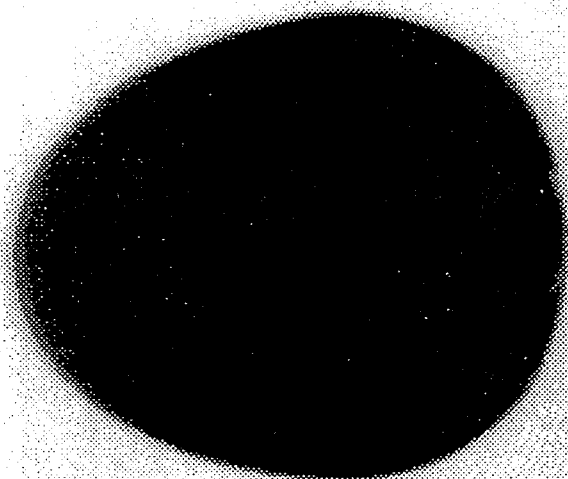
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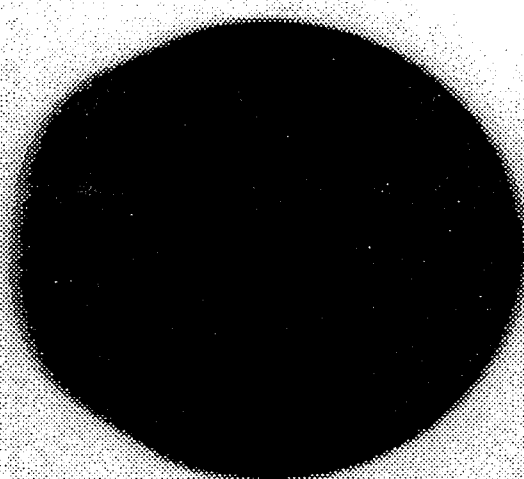
SB 13



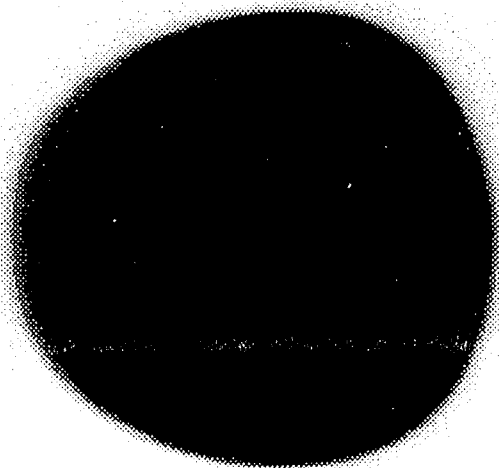
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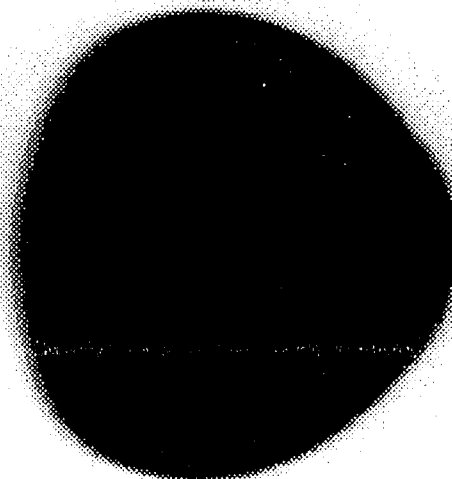
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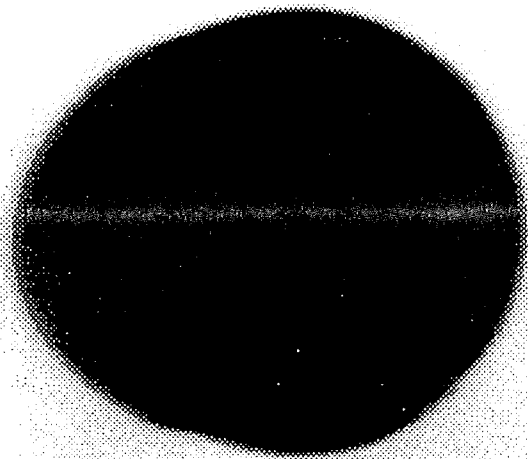
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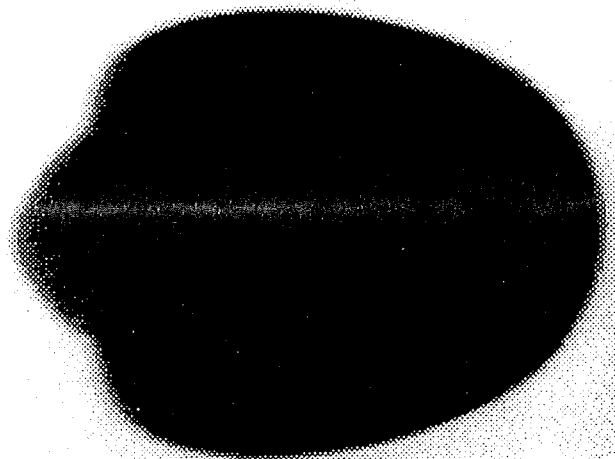
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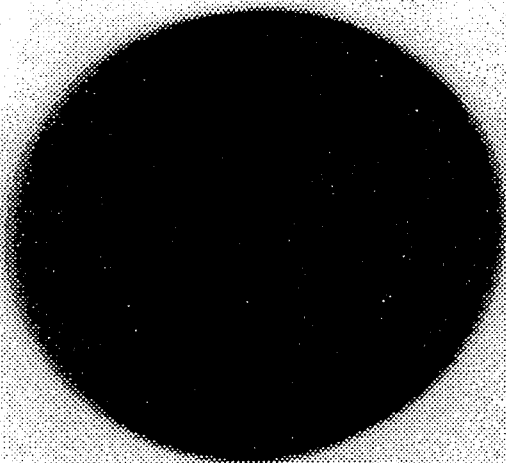
SB 22



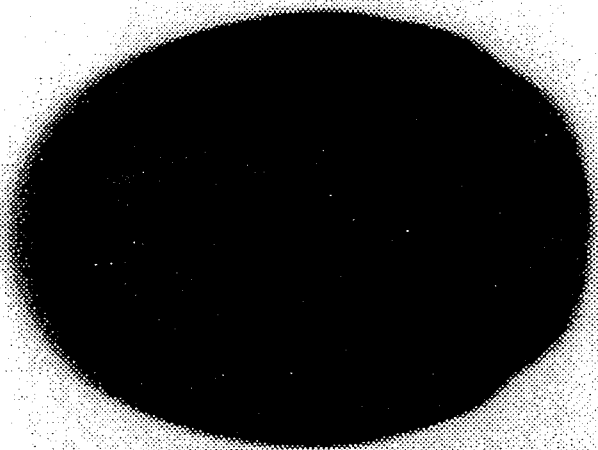
SB 23



SB 27



SB 24



SB 28



SB 26



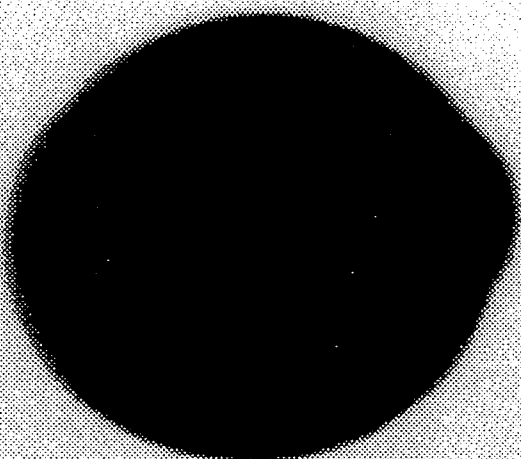
SB 29



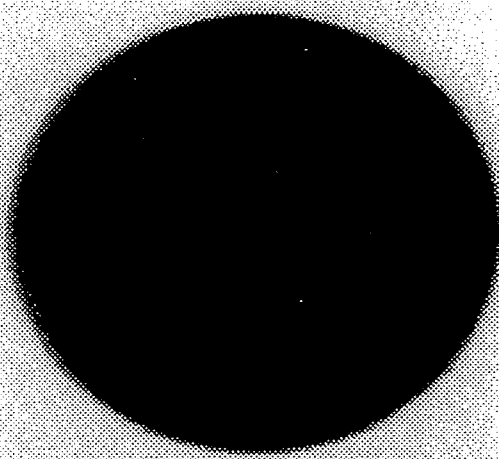
SB 30



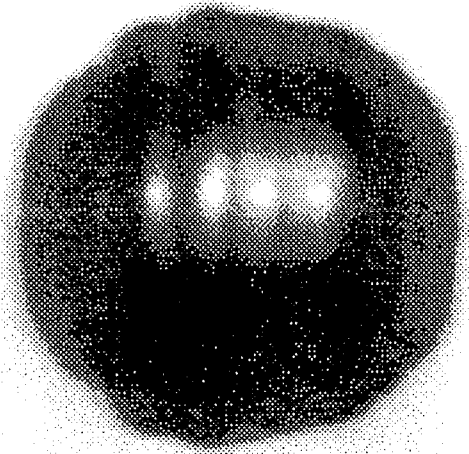
SB 31



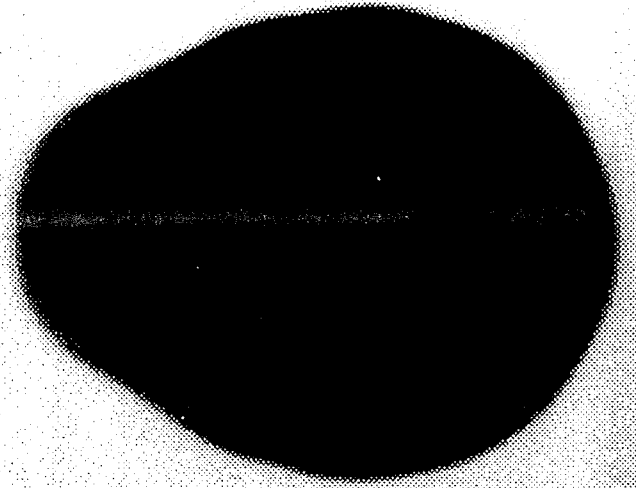
SB 32



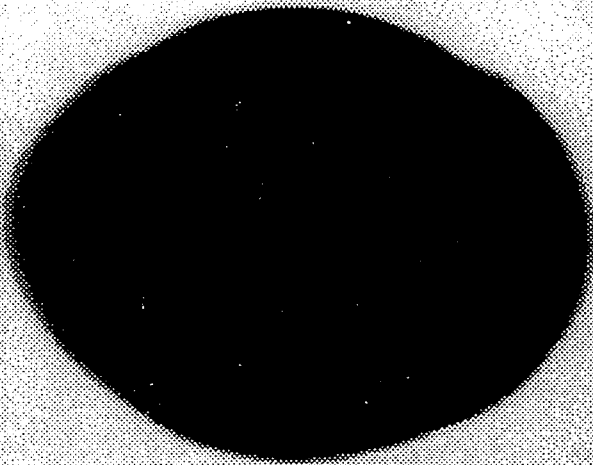
SB 43



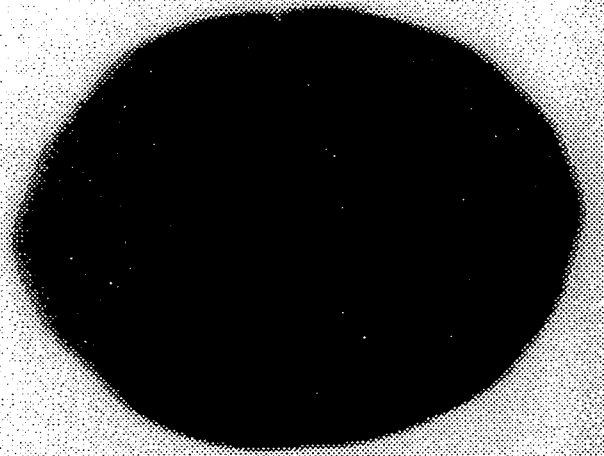
Cl 12



Cl 22



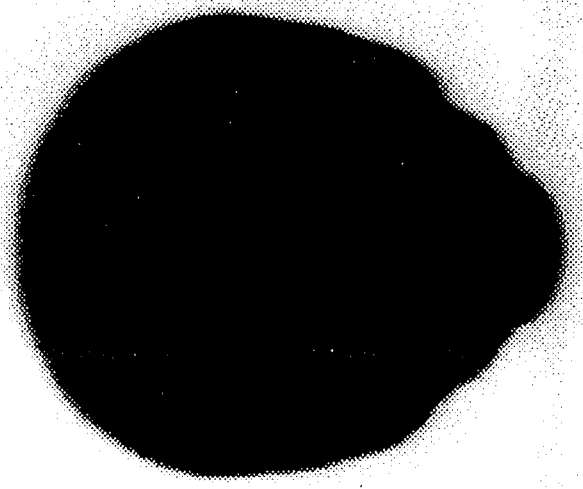
Cl 25



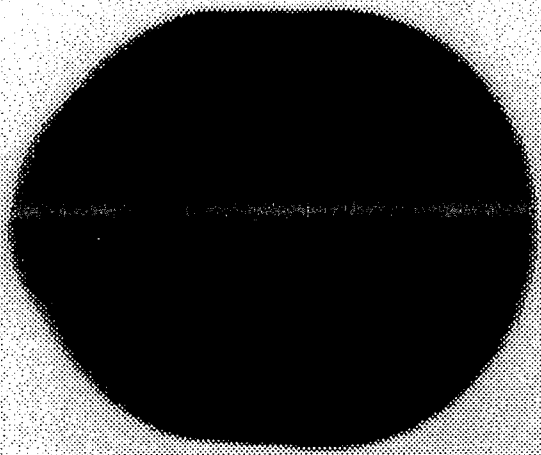
Cl 33



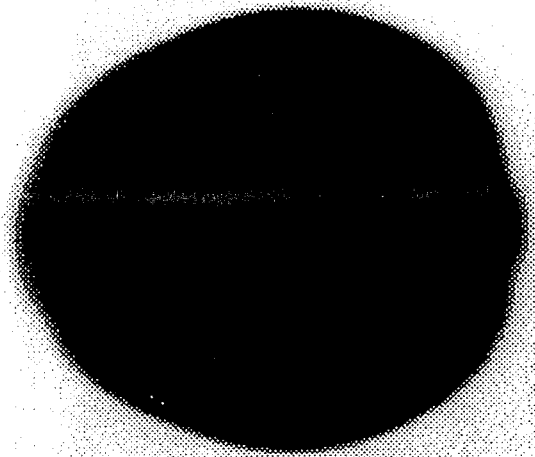
Cl 28



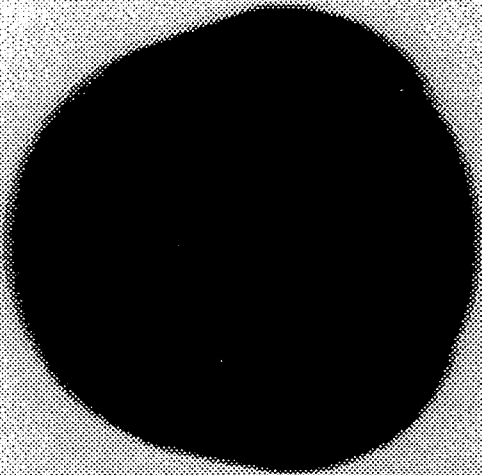
Cl 35



CI 37



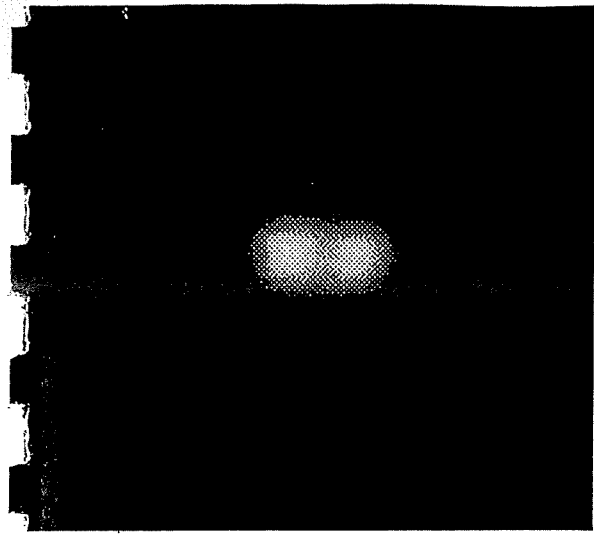
CI 48



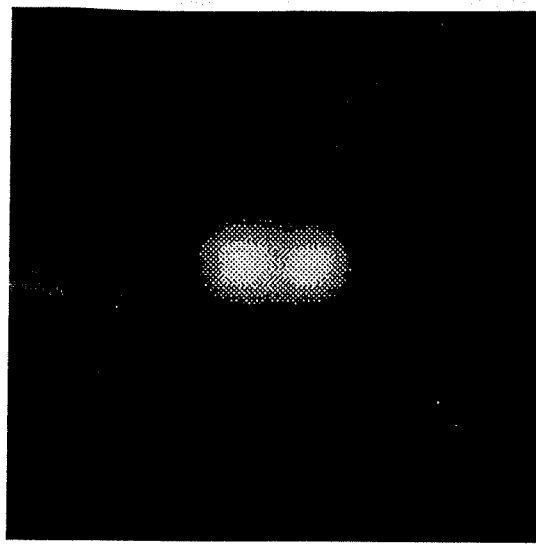
CI 39



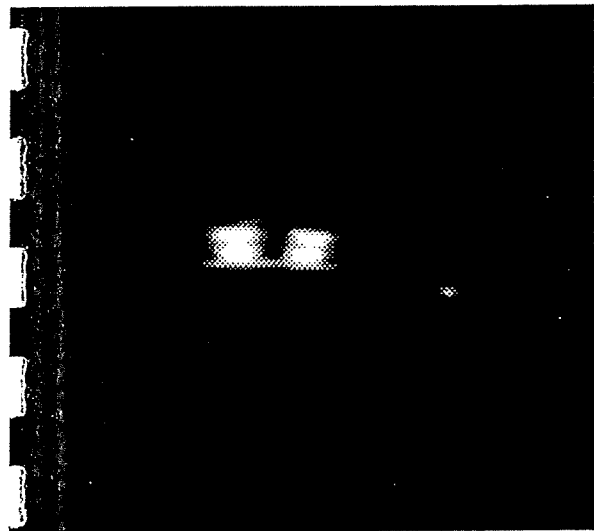
CI 49



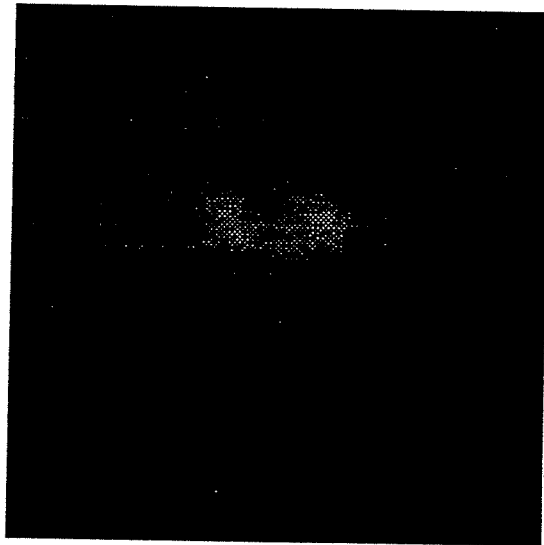
ASI Round Grade 1



AS4 Round Grade 4



Ball Bearing



Roebuck Bay
Recoverable Reject